

turning mathematical notation into beautiful diagrams

### **Katherine Ye**

Carnegie Mellon University Computer Science Department



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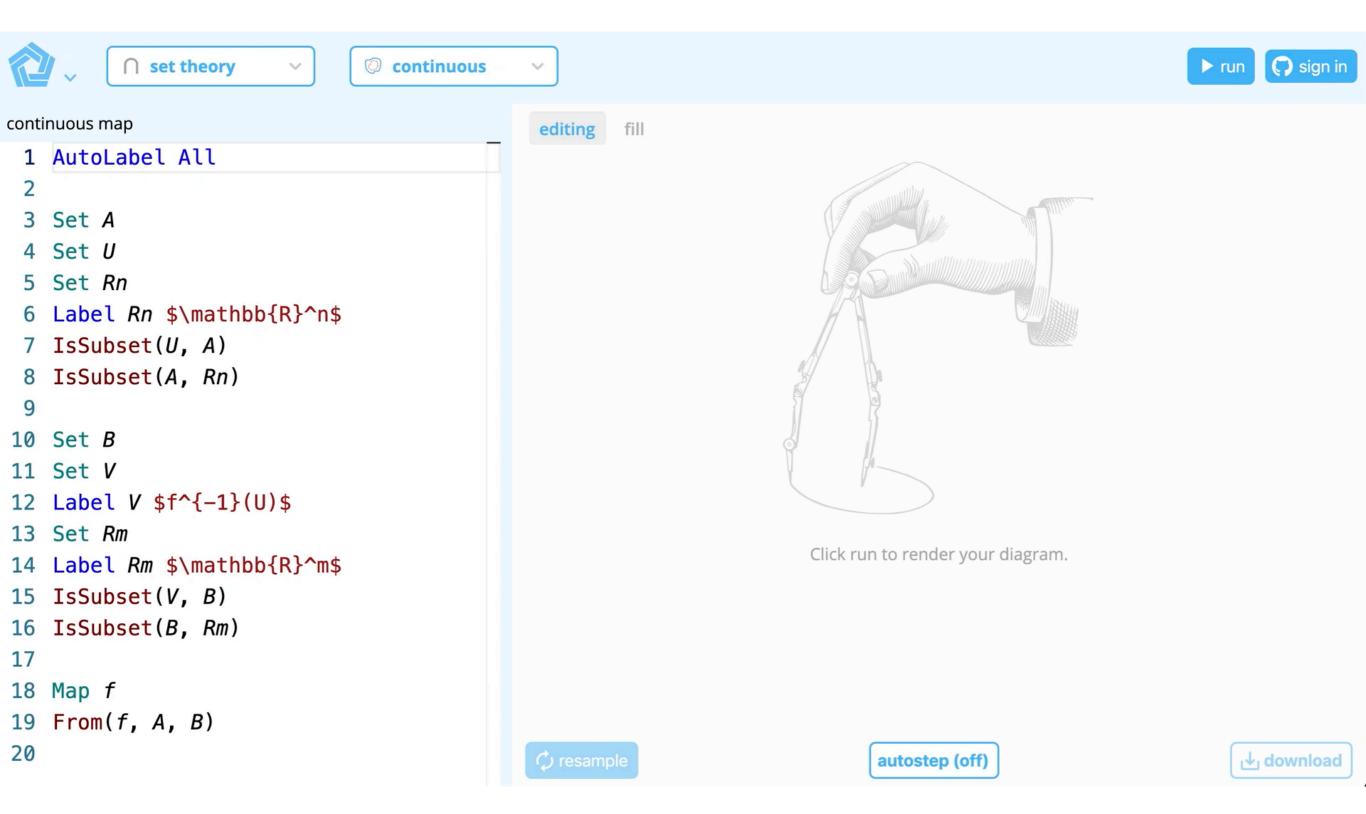


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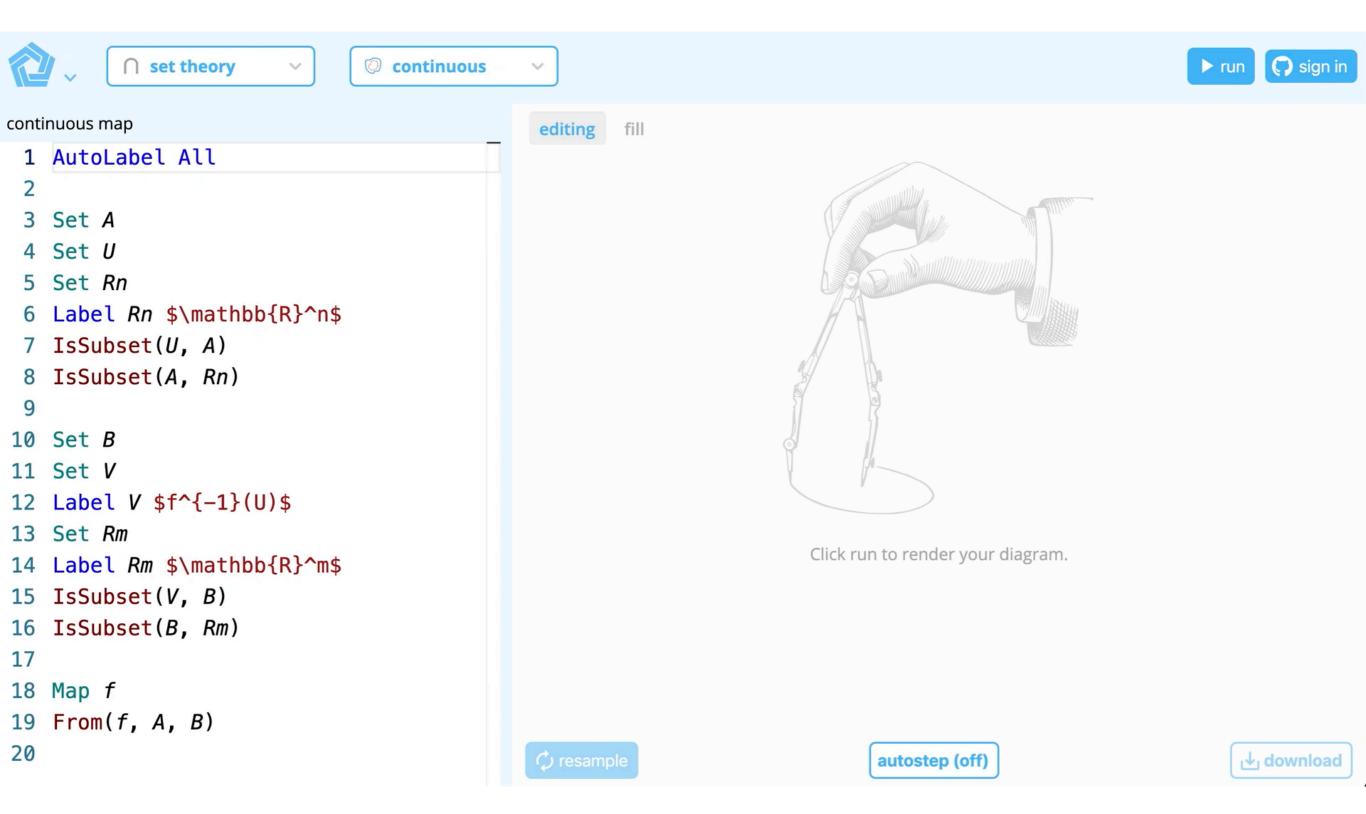
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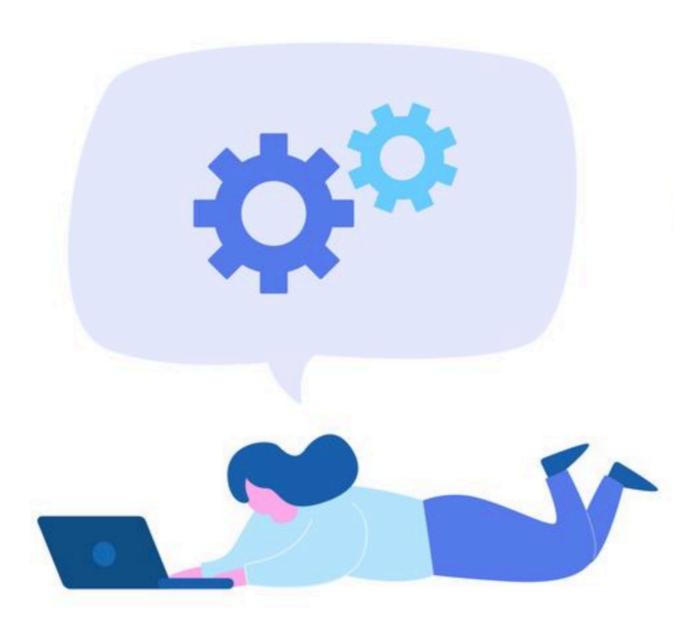
# Sneak preview:



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## Who am I?



A believer in the power of language!

## Language plays a big role in mathematics.

DIFFERENTIATION 107

### MEAN VALUE THEOREMS

5.7 Definition Let f be a real function defined on a metric space X. We say that f has a *local maximum* at a point  $p \in X$  if there exists  $\delta > 0$  such that  $f(q) \le f(p)$  for all  $q \in X$  with  $d(p, q) < \delta$ .

Local minima are defined likewise.

Our next theorem is the basis of many applications of differentiation.

5.8 Theorem Let f be defined on [a, b]; if f has a local maximum at a point  $x \in (a, b)$ , and if f'(x) exists, then f'(x) = 0.

The analogous statement for local minima is of course also true.

**Proof** Choose  $\delta$  in accordance with Definition 5.7, so that

$$a < x - \delta < x < x + \delta < b$$
.

If  $x - \delta < t < x$ , then

$$\frac{f(t) - f(x)}{t - x} \ge 0.$$

Letting  $t \to x$ , we see that  $f'(x) \ge 0$ .

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5.9 **Theorem** If f and g are continuous real functions on [a, b] which are differentiable in (a, b), then there is a point  $x \in (a, b)$  at which

$$[f(b) - f(a)]g'(x) = [g(b) - g(a)]f'(x).$$

Note that differentiability is not required at the endpoints.

Proof Put

$$h(t) = [f(b) - f(a)]g(t) - [g(b) - g(a)]f(t) \qquad (a \le t \le b).$$

Then h is continuous on [a, b], h is differentiable in (a, b), and

(12) 
$$h(a) = f(b)g(a) - f(a)g(b) = h(b).$$

To prove the theorem, we have to show that h'(x) = 0 for some  $x \in (a, b)$ . If h is constant, this holds for every  $x \in (a, b)$ . If h(t) > h(a) for some  $t \in (a, b)$ , let x be a point on [a, b] at which h attains its maximum

### 108 PRINCIPLES OF MATHEMATICAL ANALYSIS

(Theorem 4.16). By (12),  $x \in (a, b)$ , and Theorem 5.8 shows that h'(x) = 0. If h(t) < h(a) for some  $t \in (a, b)$ , the same argument applies if we choose for x a point on [a, b] where h attains its minimum.

This theorem is often called a *generalized mean value theorem*; the following special case is usually referred to as "the" mean value theorem:

**5.10 Theorem** If f is a real continuous function on [a, b] which is differentiable in (a, b), then there is a point  $x \in (a, b)$  at which

$$f(b) - f(a) = (b - a)f'(x).$$

**Proof** Take g(x) = x in Theorem 5.9.

- **5.11 Theorem** Suppose f is differentiable in (a, b).
  - (a) If  $f'(x) \ge 0$  for all  $x \in (a, b)$ , then f is monotonically increasing.
  - (b) If f'(x) = 0 for all  $x \in (a, b)$ , then f is constant.
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**Proof** All conclusions can be read off from the equation

$$f(x_2) - f(x_1) = (x_2 - x_1)f'(x),$$

which is valid, for each pair of numbers  $x_1, x_2$  in (a, b), for some x between  $x_1$  and  $x_2$ .

### THE CONTINUITY OF DERIVATIVES

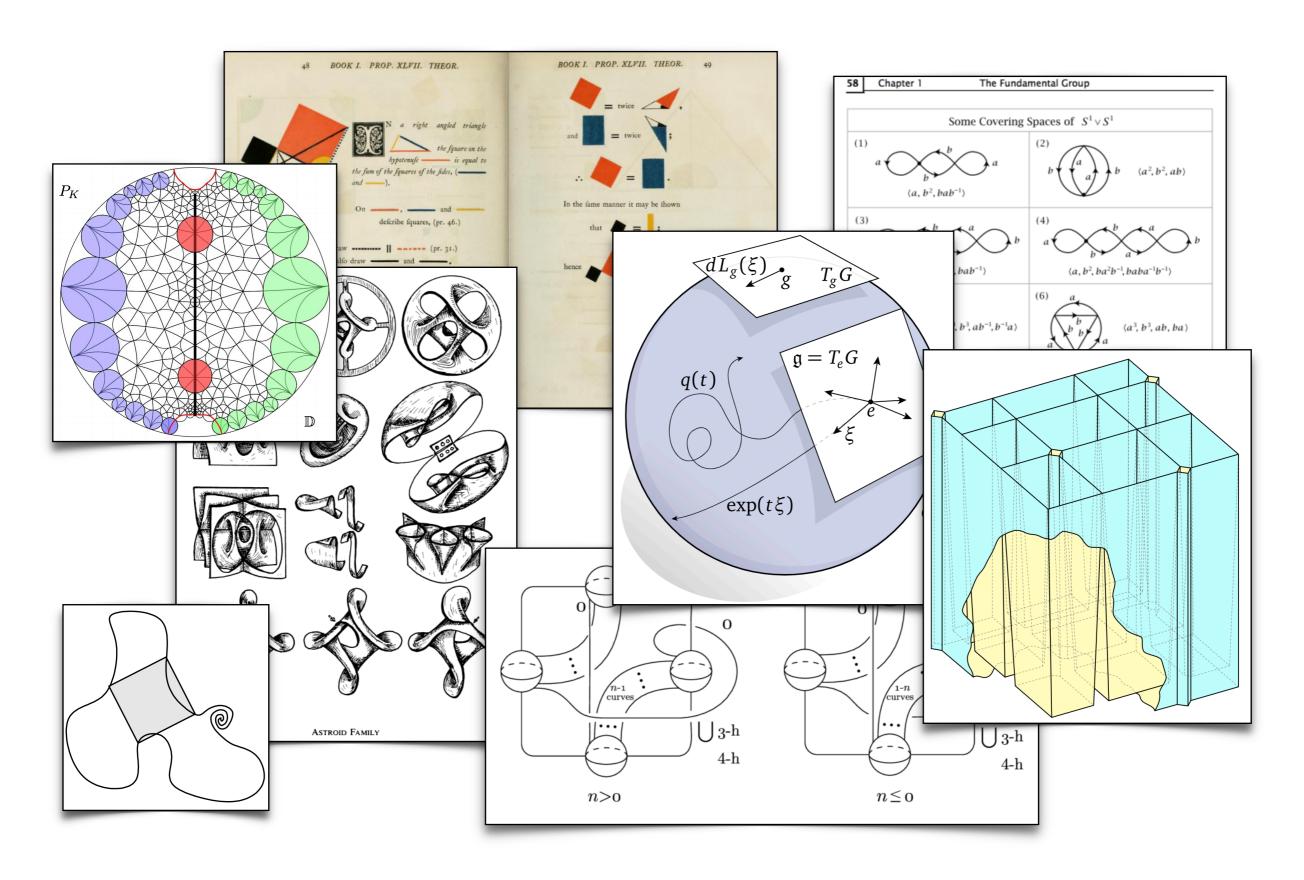
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**5.12 Theorem** Suppose f is a real differentiable function on [a, b] and suppose  $f'(a) < \lambda < f'(b)$ . Then there is a point  $x \in (a, b)$  such that  $f'(x) = \lambda$ .

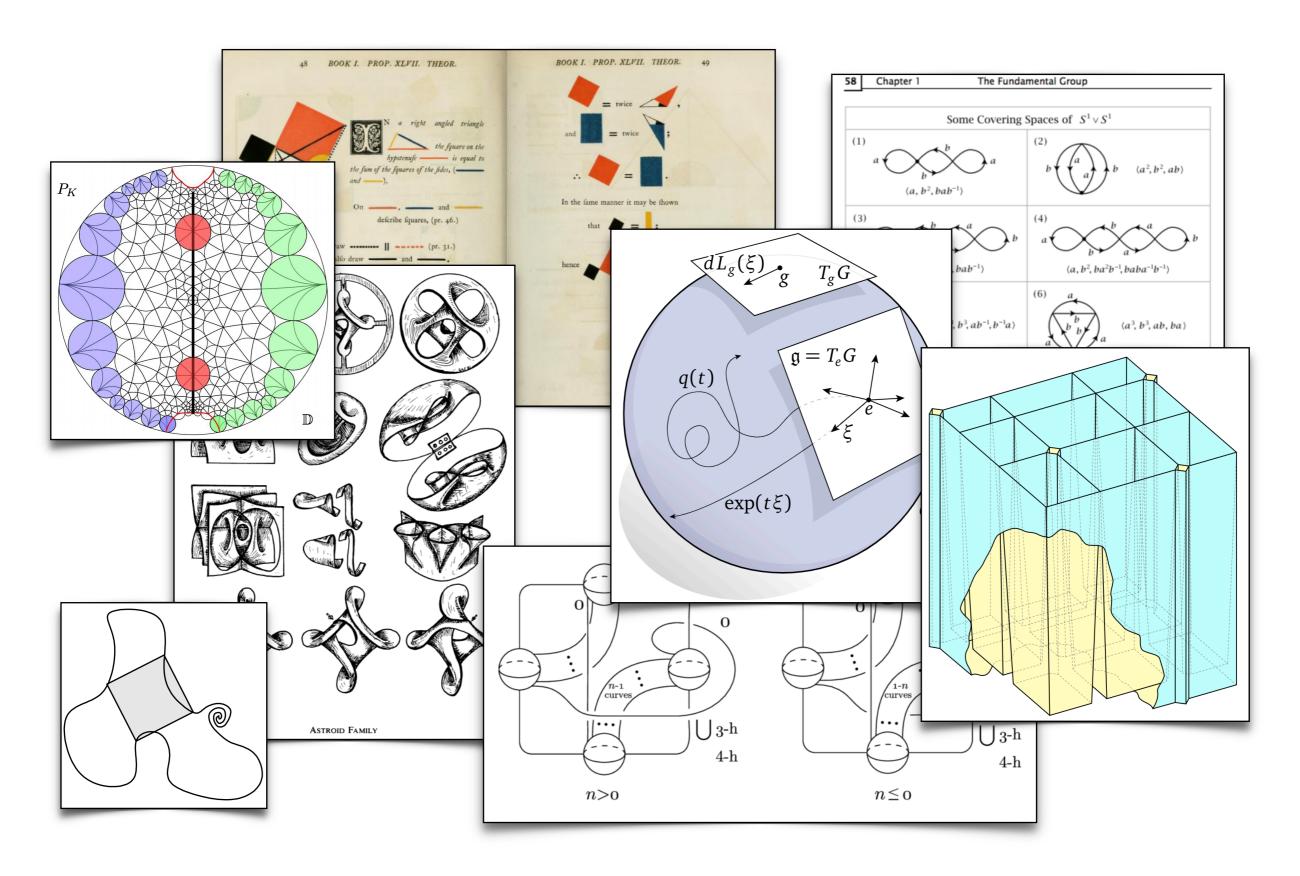
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**Proof** Put  $g(t) = f(t) - \lambda t$ . Then g'(a) < 0, so that  $g(t_1) < g(a)$  for some  $t_1 \in (a, b)$ , and g'(b) > 0, so that  $g(t_2) < g(b)$  for some  $t_2 \in (a, b)$ . Hence g attains its minimum on [a, b] (Theorem 4.16) at some point x such that a < x < b. By Theorem 5.8, g'(x) = 0. Hence  $f'(x) = \lambda$ .

# But it's not the whole story



# But it's not the whole story picture.





"People have very powerful facilities for taking in information visually...

On the other hand, they do not have a good built-in facility for turning an internal spatial understanding back into a two-dimensional image.

So mathematicians usually have fewer and poorer figures in their papers and books than in their heads."

### **William Thurston**

(probably trying to make a diagram in Powerpoint)

Question: How can we do a better job of connecting language and visualization?

Idea: design a programming language to reflect the way people already naturally talk about a domain.

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### **MATLAB**

$$\begin{pmatrix} 1 & 0 & & & 0 \\ 1 & -2 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & -2 & 1 \\ 0 & & & -2 & 2 \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \\ \vdots \\ V_{J-1} \\ V_J \end{pmatrix} = \begin{pmatrix} 0 \\ (\Delta x)^2 f_2 \\ \vdots \\ (\Delta x)^2 f_{J-1} \\ (\Delta x)^2 f_J \end{pmatrix}$$

$$\mathbf{b} = 2 * \mathbf{c} + \mathbf{d}$$

$$\mathbf{x} = \mathbf{A} \setminus \mathbf{b}$$

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### TeX

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```
\int M d\omega =
\int {\partial M}
     \omega
```

### **CSS**

```
http://penrose.ink
```

```
link {
  font-size: large;
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```

# Good news: we already have a nice language for mathematics

DIFFERENTIATION 107

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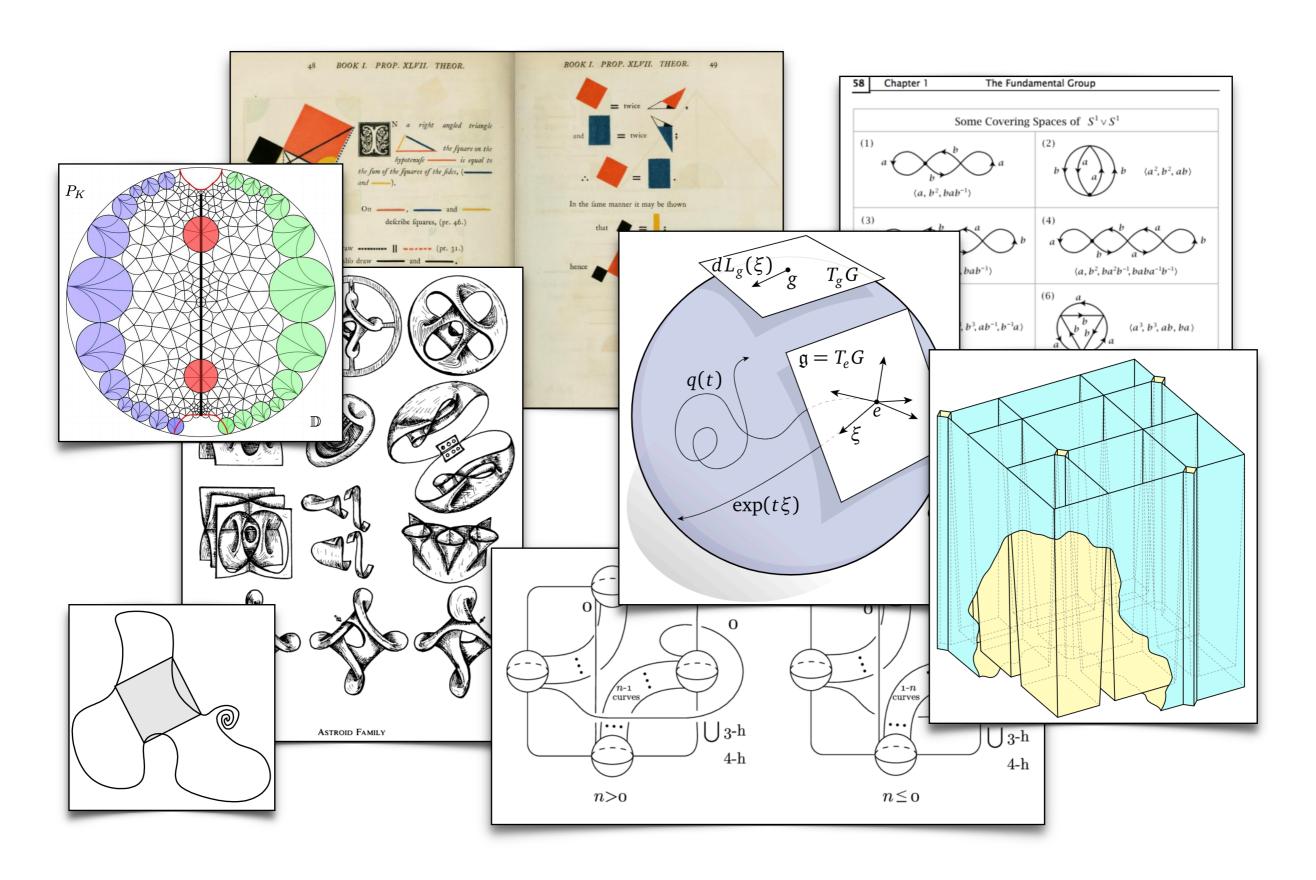
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## Still need to connect this language to pictures!



# How do we get there?

### **Outline of this talk:**

- I. What do we want from a diagramming tool?
- II. What do tools look like now?
- III. A new language-based tool
- IV. What does a language-based approach enable?

Part I: What makes a good tool?

Picture an ideal tool for making mathematical diagrams...



...what features might it have?







**Universality**: it should be extensible, i.e., able to generate diagrams from any area of math, using any visual representation





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**Productivity**: it should be reasonably <u>fast</u> to make or change diagrams

Solve hard problems
 (e.g., prove Fermat's last theorem)

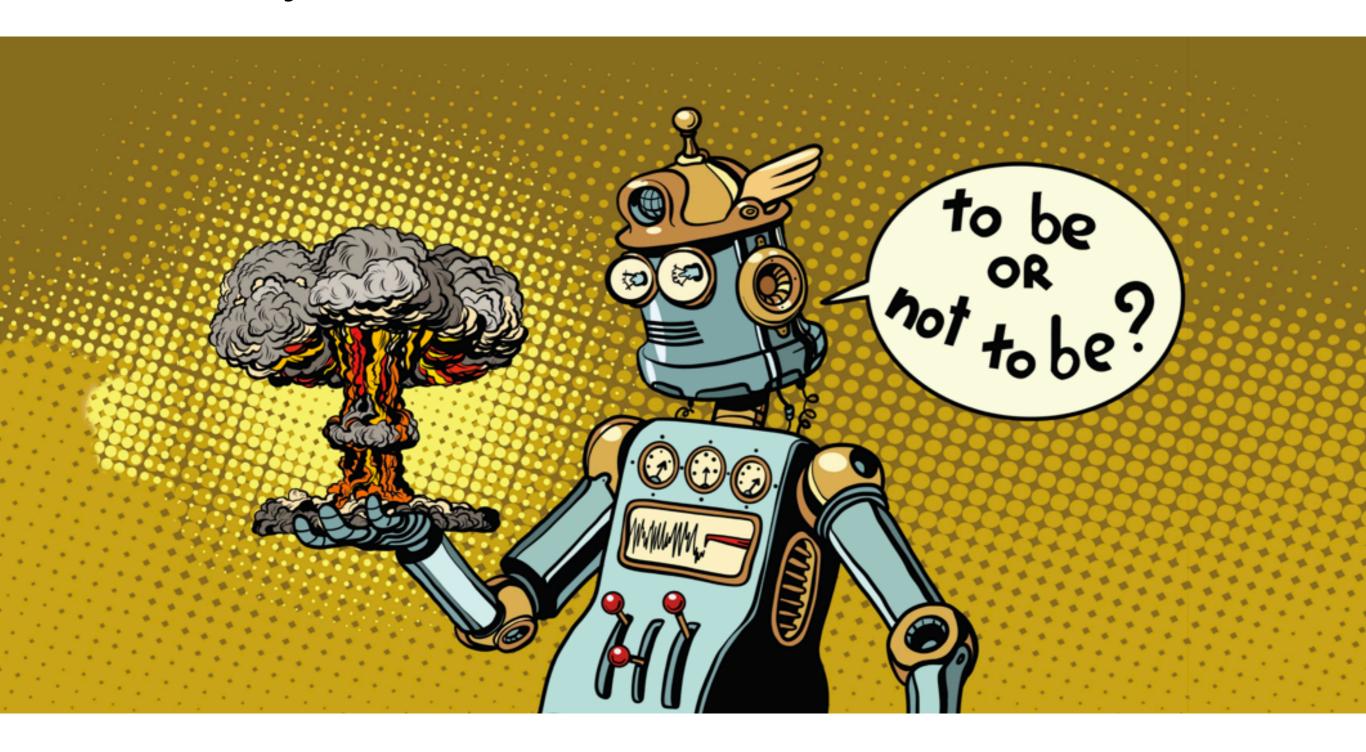
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   (e.g., prove Fermat's last theorem)
- Invent novel visualization methods (e.g., sphere eversion)
- Guarantee that diagrams formally encode mathematics
- Provide unified notation for all of mathematics



In general: shouldn't expect your diagramming tool to do things that even <u>expert</u> mathematicians can't do!

Does such a holy grail exist?

Let's take a look at the state of the art...

Part II: What do tools look like now?



# DIAGRAM TOOL OLYMPICS



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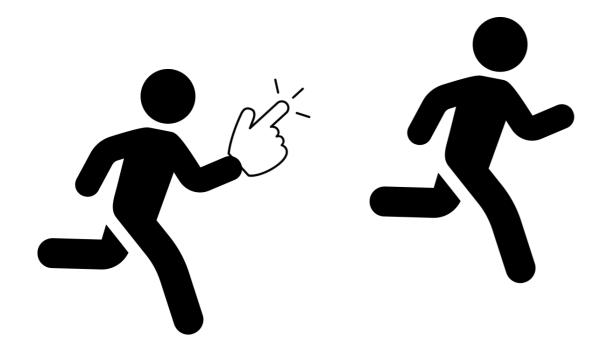




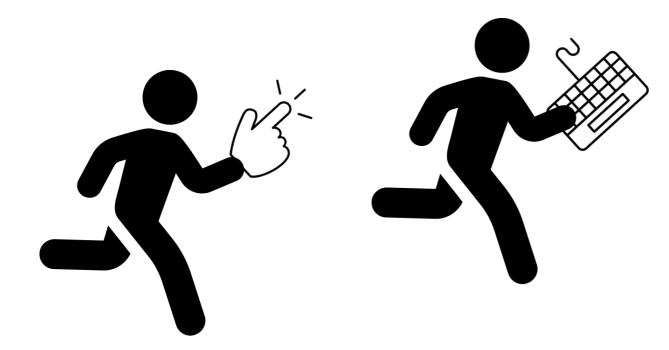
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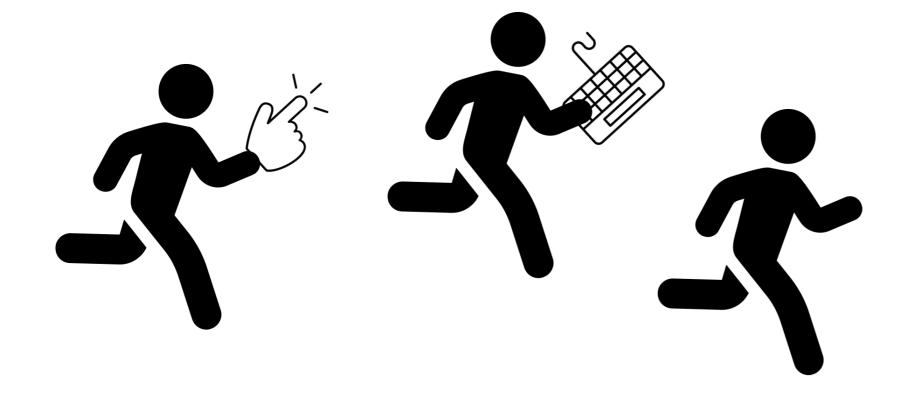






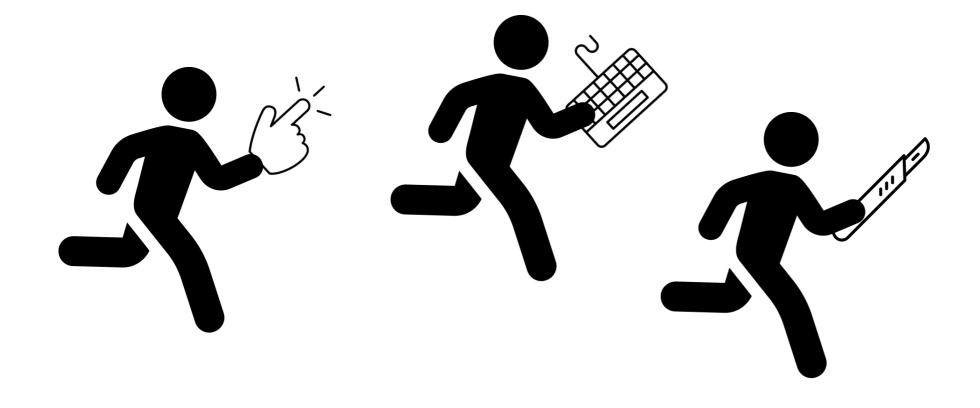






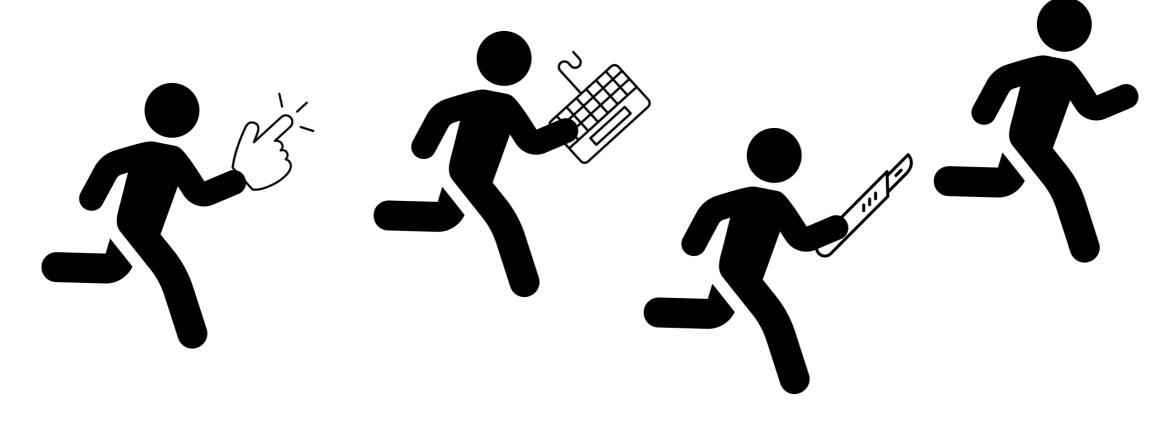


Providence 2019





Providence 2019





Providence 2019





## Graphical User Interface (GUI)

Examples: Adobe Illustrator, Inkscape

#### Lots of clicking and dragging... (sped up 40x)



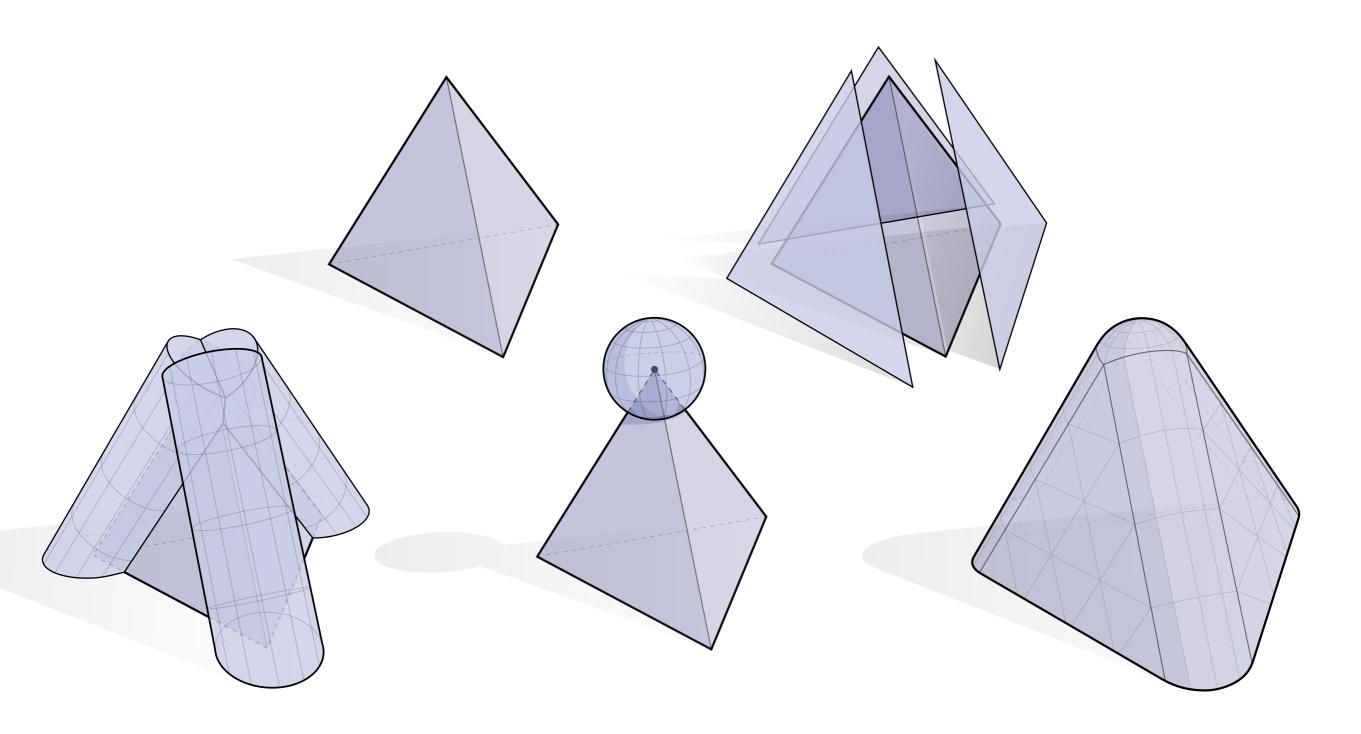
Very hard to change mathematical content later!

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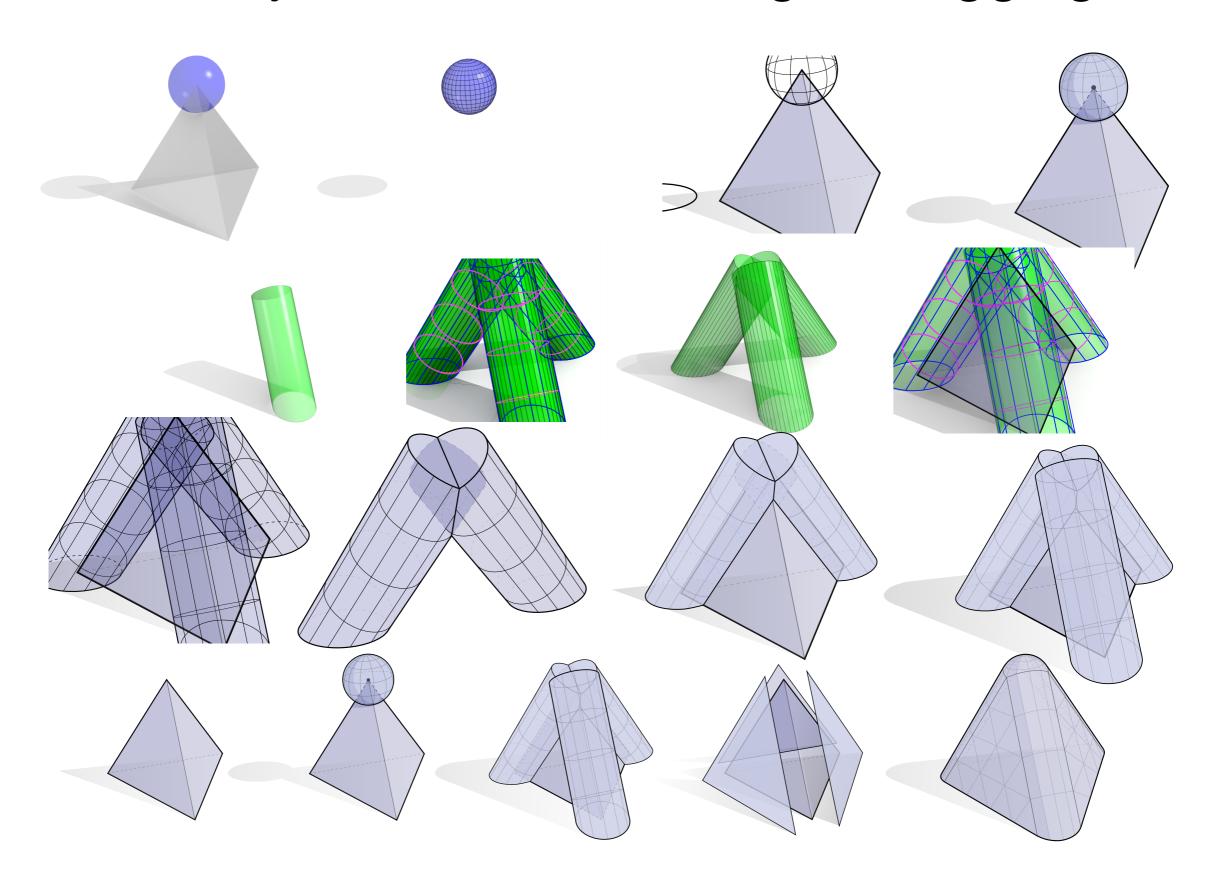
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#### Example: Illustrating Steiner's polyhedral formula



Looks easy, right?

Reality: 8 hours of clicking & dragging



Source: Keenan Crane



Accessibility



Universality



**Beauty** 









**Accessibility** 



Universality



**Beauty** 









Accessibility



Universality



**Beauty** 









Accessibility



Universality



**Beauty** 









Accessibility



Universality



**Beauty** 









Examples: PostScript, TikZ

```
\documentclass{article}
\usepackage{tikz}
\begin{document}
\pagestyle{empty}
\begin{tikzpicture}
    \begin{scope}[shift={(3cm,-5cm)}, fill opacity=0.5]
    \draw[fill=red, draw = black] (0,0) circle (5);
    \draw[fill=green, draw = black] (-1.5,0) circle (3);
    \draw[fill=blue, draw = black] (1.5,0) circle (3);
    \node at (0,4) (A) {\large\textbf{A}};
    \node at (-2,1) (B) {\large\textbf{B}};
    \node at (2,1) (C) {\large\textbf{C}};
    \node at (0,0) (D) {\large\textbf{D}};
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\documentclass{article}
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    \draw[fill=red, draw = black
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Low-level specification of coordinates

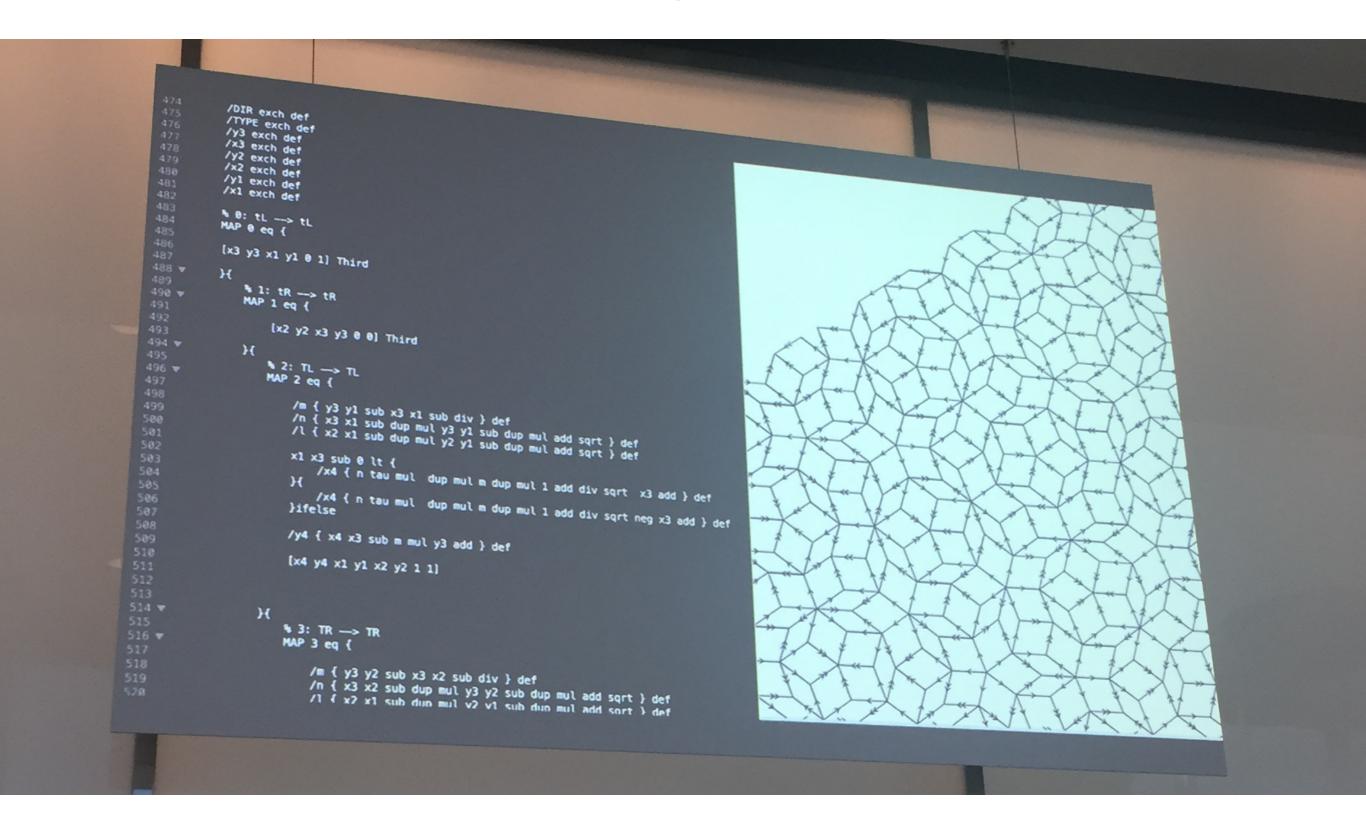
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\en
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Also hard to modify mathematical content

#### Can however handle significant complexity...





**Accessibility** 



Universality



**Beauty** 









**Accessibility** 



Universality



**Beauty** 









**Accessibility** 



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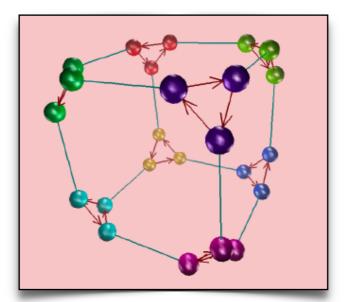




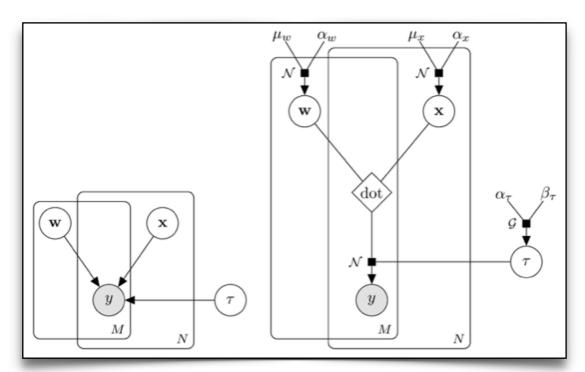


Examples: KnotPlot, Group Explorer

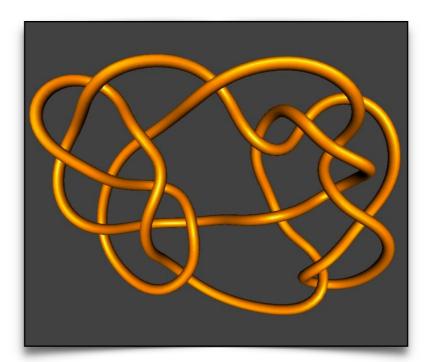
#### More examples



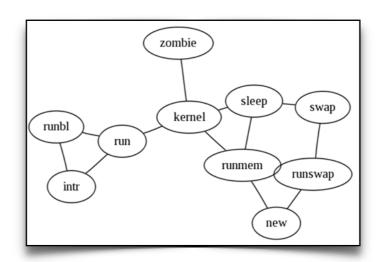
**Group Explorer** 



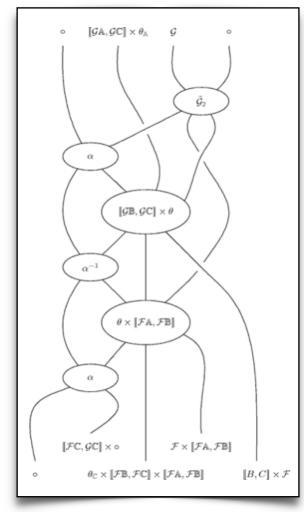
**BayesNet** 



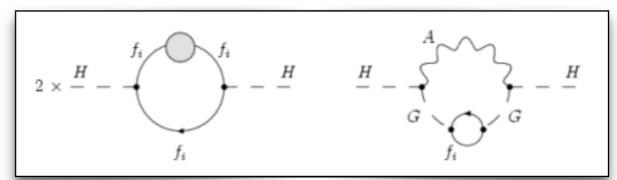
**KnotPlot** 



GraphViz



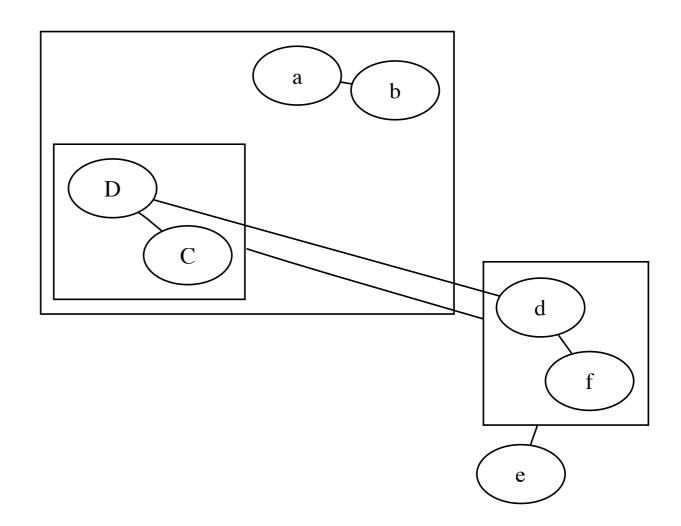
strid



**JaxoDraw** 

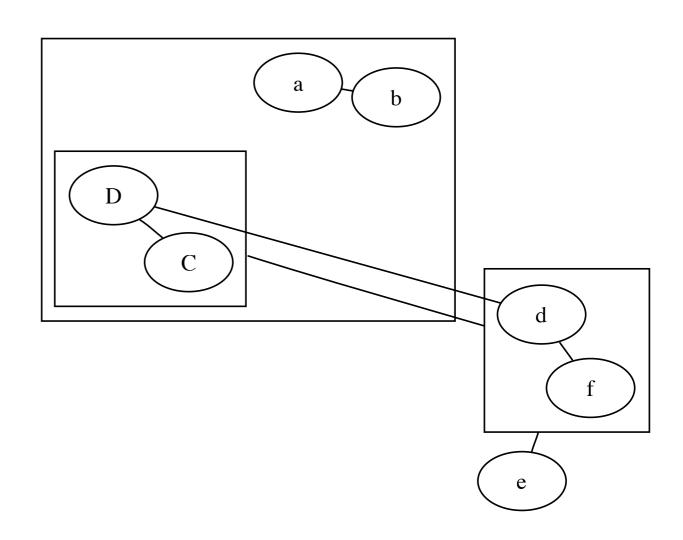
#### Example: graph visualization using Graphviz

```
graph G {
  e
  subgraph clusterA {
    a -- b;
    subgraph clusterC {
      C -- D;
  subgraph clusterB {
    d -- f
  e -- clusterB
  clusterC -- clusterB
```



#### Example: graph visualization using Graphviz

```
graph G {
  e
  subgraph clusterA {
    a -- b;
    subgraph clusterC {
      C -- D;
  subgraph clusterB {
    d -- f
  e -- clusterB
  clusterC -- clusterB
```



High-level & clean—but only works for graphs!



**Accessibility** 



Universality



**Beauty** 









**Accessibility** 



Universality



**Beauty** 









**Accessibility** 



Universality



**Beauty** 









**Accessibility** 



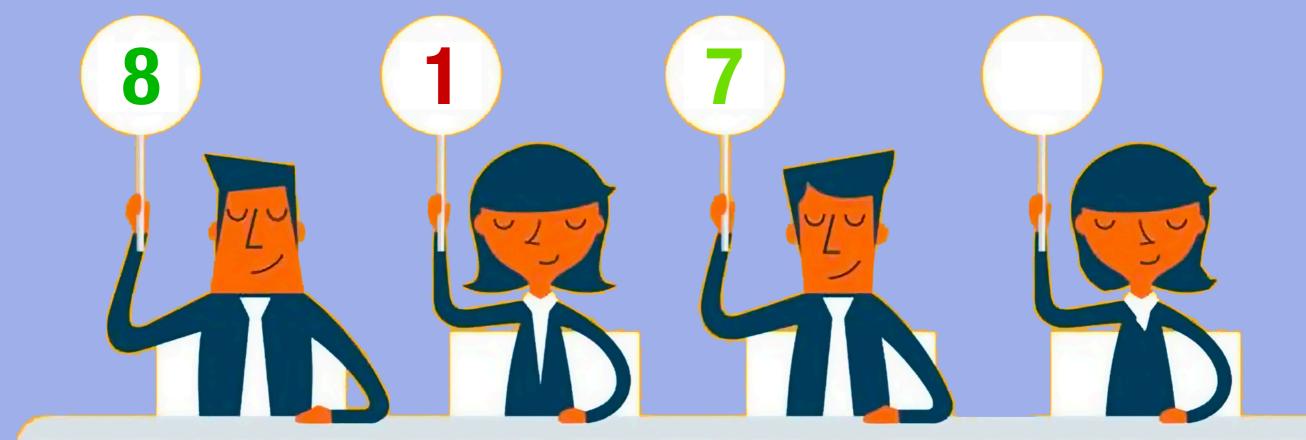
Universality



**Beauty** 









**Accessibility** 



Universality



**Beauty** 



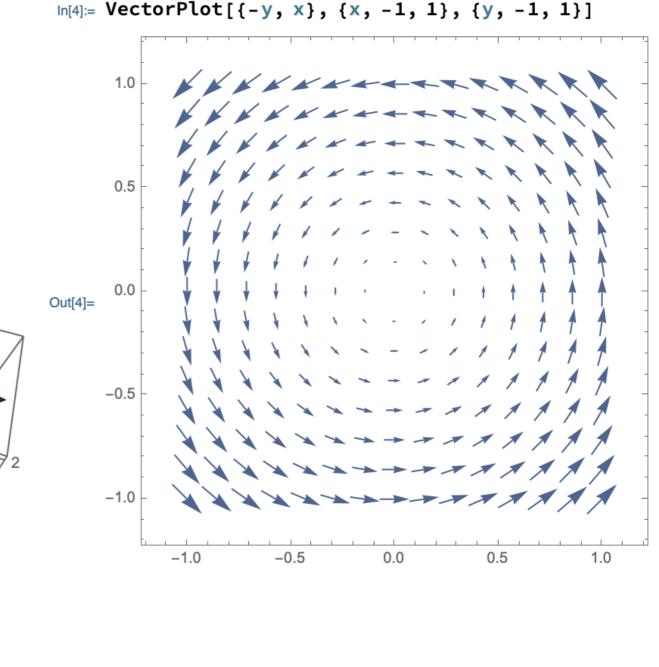


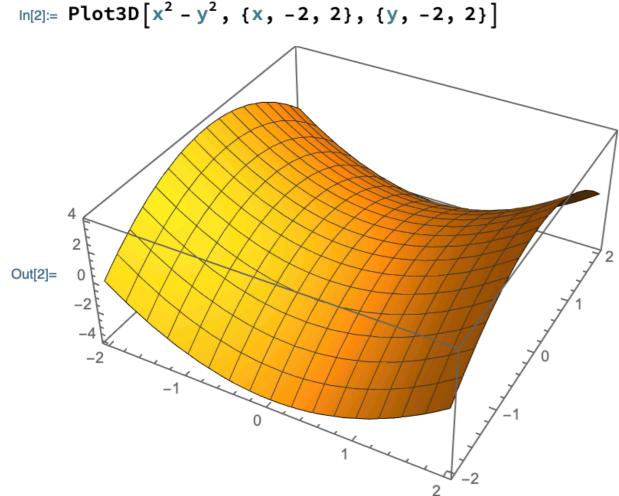




Examples: Matplotlib, MATLAB

#### Example: Mathematica

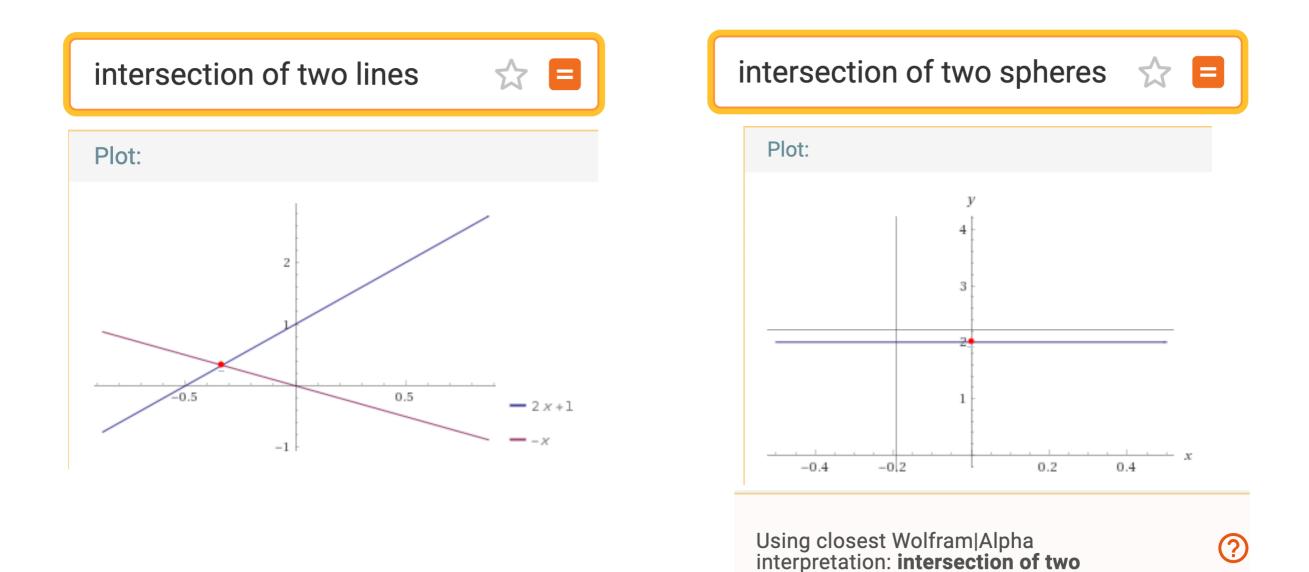




Still need to give explicit coordinates

Meaning of expressions easily lost

#### Example: Wolfram Alpha

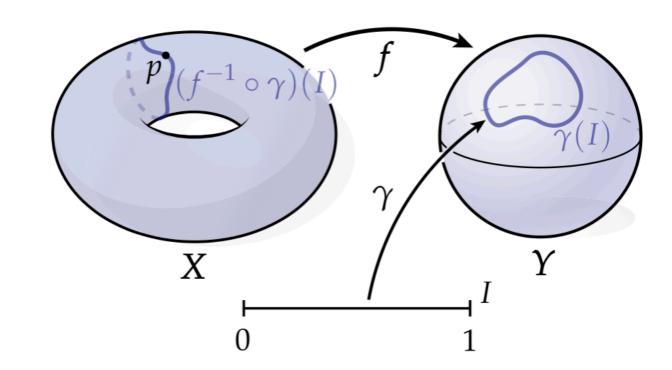


Handles more conceptual statements

Cases it can handle are fairly "canned"...

#### Imagine attempting something like this\*...

```
TopologicalSpace X,Y
π1(X) = DirectProduct(Ints,Ints)
π1(Y) = TrivialGroup
I := [0,1] Subset Reals
ContinuousMap f : X -> Y
ContinuousMap gamma : I -> Y
gamma(0) = gamma(1)
eta1 = Image(gamma)
eta2 = PreImage(eta1,f)
p In eta1
```





**Accessibility** 



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**Accessibility** 



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**Beauty** 









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**Accessibility** 



Universality



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# Diagramming is still hard!

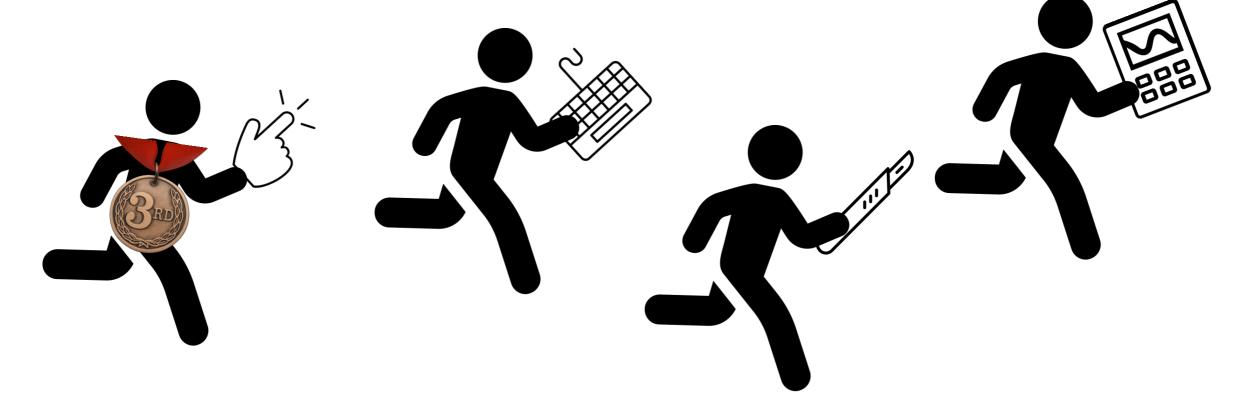


Providence 2019





Providence 2019















Part III: A new language-based tool

Work in progress!

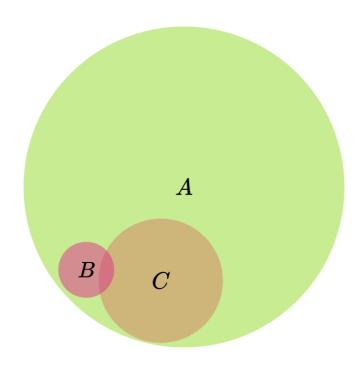
Part III: A new language-based tool

Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

one style

Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

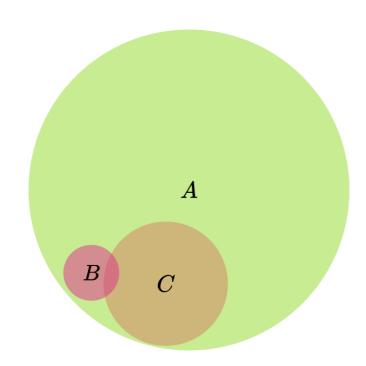
one style



Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

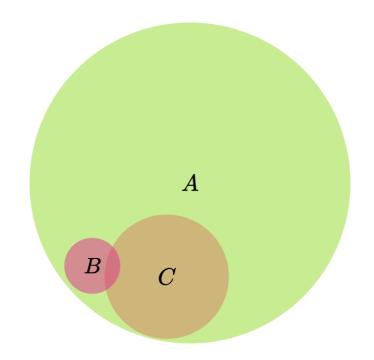
one style

another style

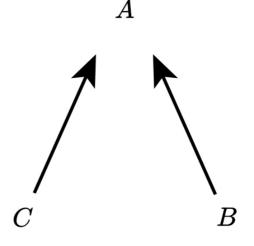


Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

one style



another style

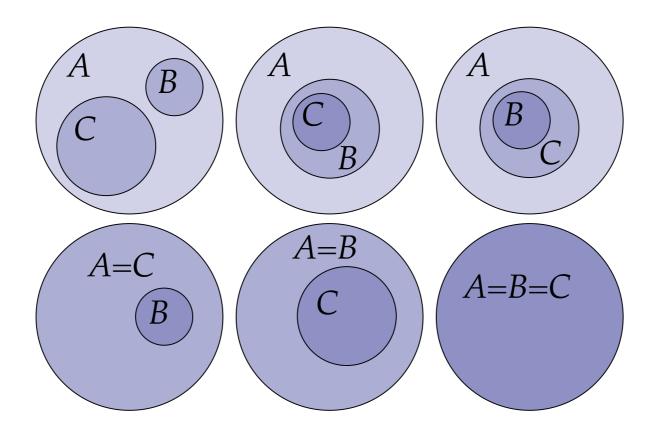


Also: miss a lot of possibilities if you draw just one diagram...

$$B \subseteq A$$
 and  $C \subseteq A$ 

Also: miss a lot of possibilities if you draw just one diagram...

$$B \subseteq A$$
 and  $C \subseteq A$ 



# Let's try this in Penrose (demo)

Question: How can we do a better job of connecting language and visualization?

Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

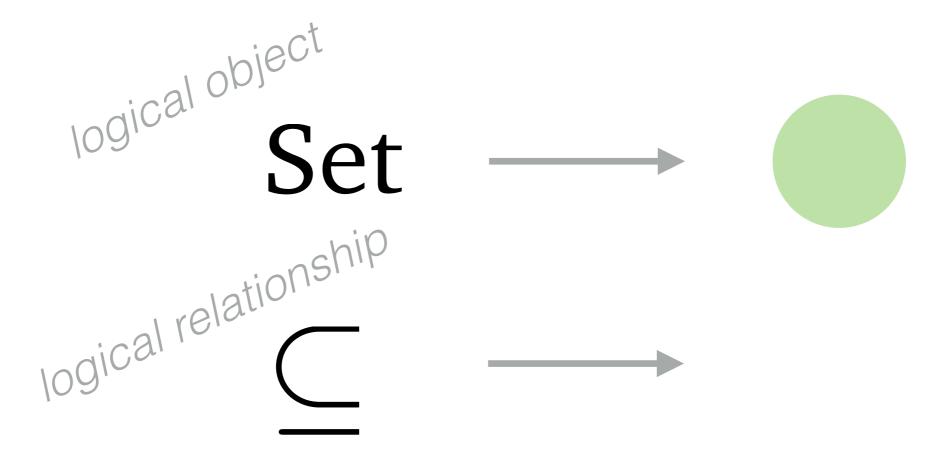
Set

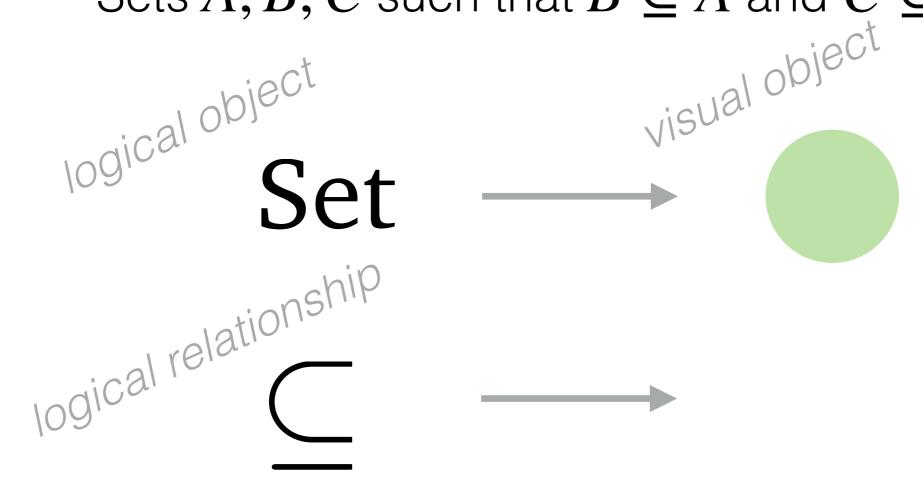
Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

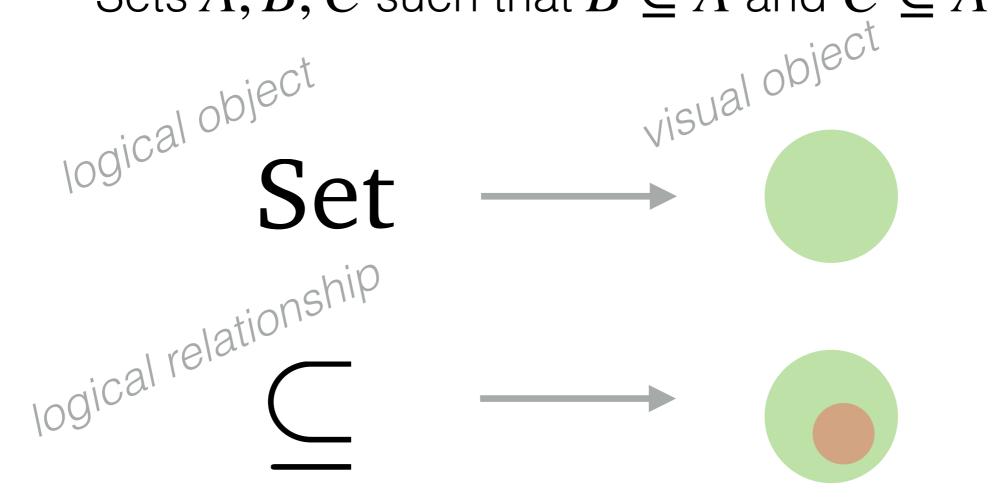
logical object

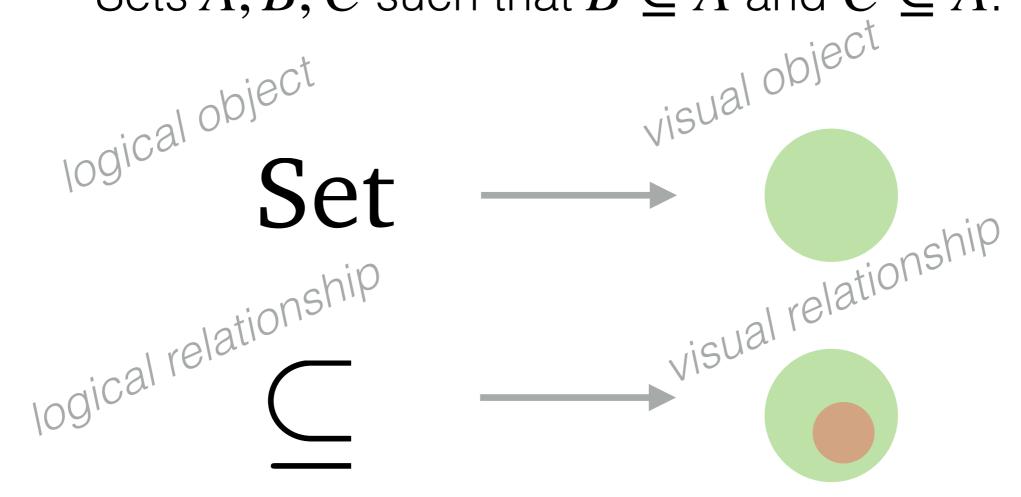
Set

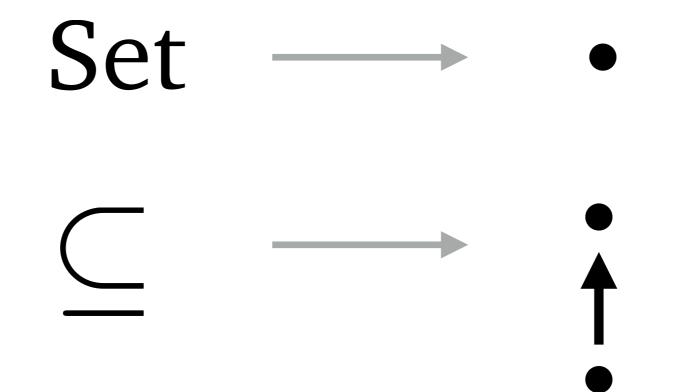




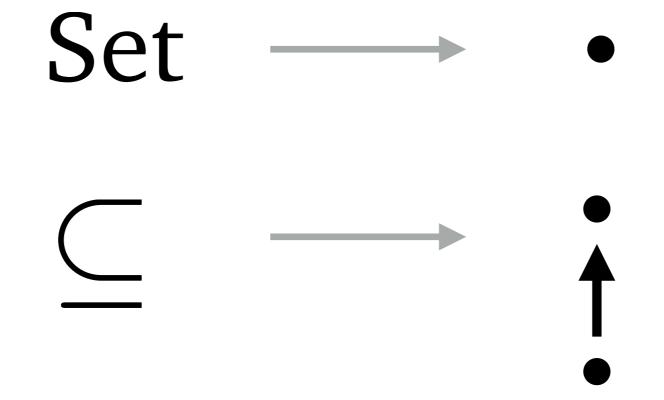




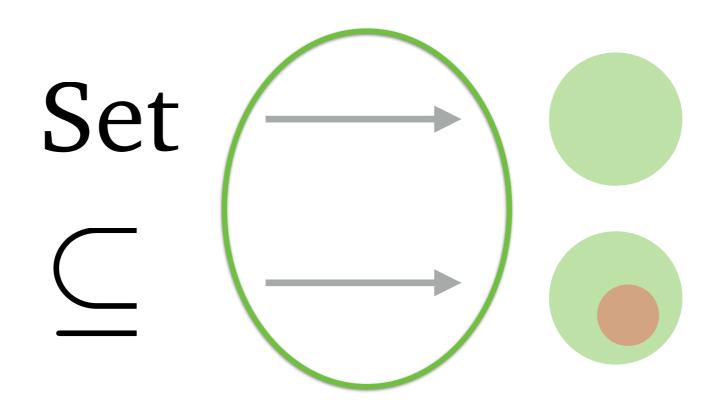




Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .

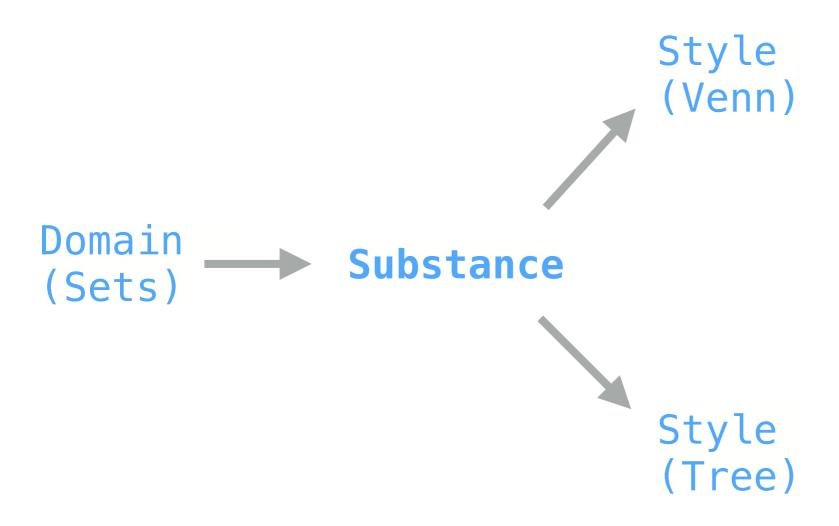


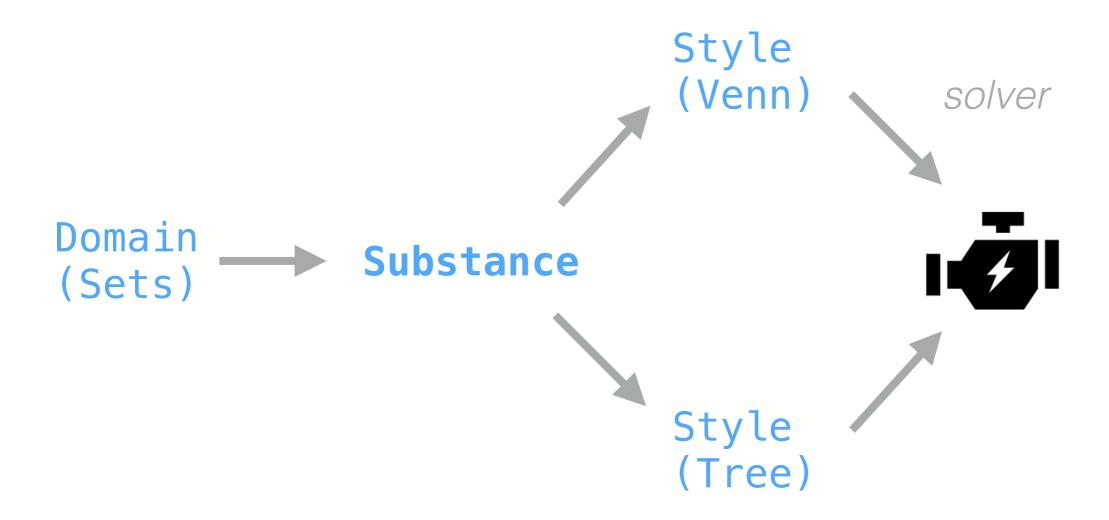
It is powerful to formally encode the **mapping** from abstract objects and relationships to their visual representations.

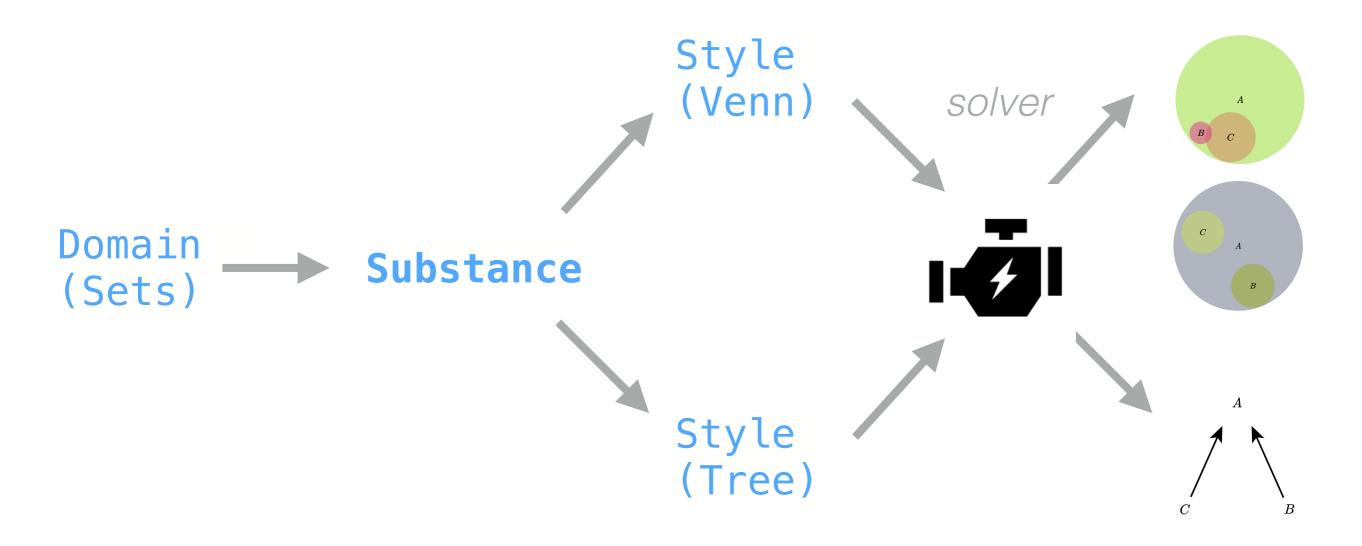


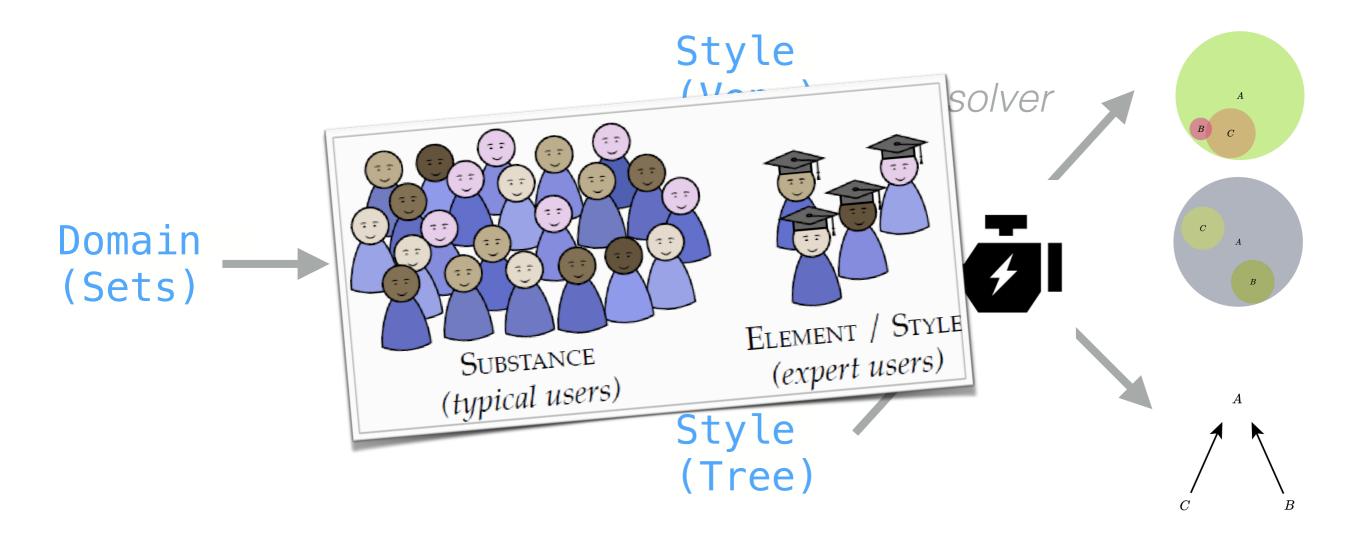
Domain
(Sets)

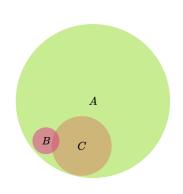
Domain (Sets) Substance

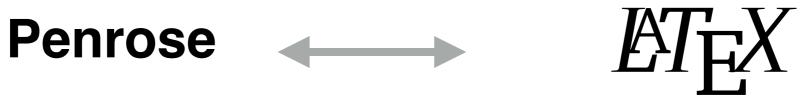


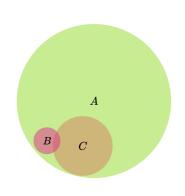








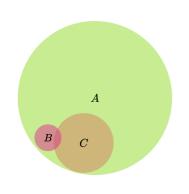




Domain



(no analogy)





Domain

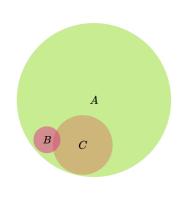


(no analogy)

Substance



TeX file





Domain

 $\qquad \qquad +$ 

(no analogy)

Substance

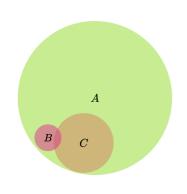


TeX file

Style



TeX style





Domain

 $\quad \qquad \longrightarrow \quad$ 

(no analogy)

Substance



TeX file

Style

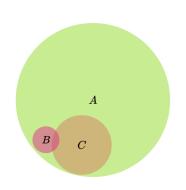


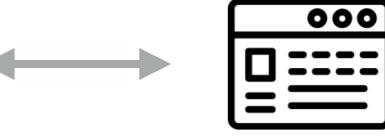
TeX style

solver

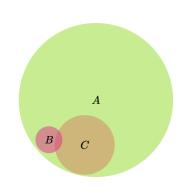


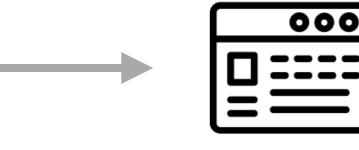
TeX layout engine





## Web design



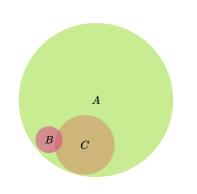


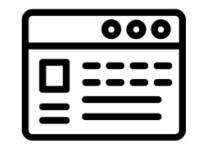
## Web design

Domain



(no analogy)





## Web design

Domain

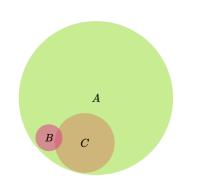


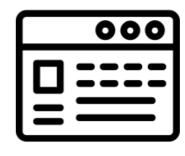
(no analogy)

Substance



HTML





## Web design

Domain



(no analogy)

Substance

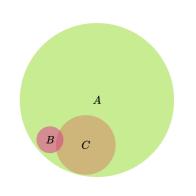


HTML

Style



CSS





## Web design

Domain



(no analogy)

Substance



HTML

Style



CSS

solver



browser layout engine

# A deeper dive with another example

type VectorSpace

type VectorSpace
type Vector

type VectorSpace
type Vector

```
type VectorSpace
type Vector
```

predicate In : Vector v \* VectorSpace V

```
type VectorSpace
type Vector
```

```
predicate In : Vector v * VectorSpace V
function addV : Vector * Vector -> Vector
```

```
type VectorSpace
type Vector
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function addV : Vector * Vector -> Vector
```

```
type VectorSpace
type Vector
```

```
predicate In : Vector v * VectorSpace V
function addV : Vector * Vector -> Vector
```

notation "Vector a ∈ U" ~ "Vector a; In(a,U)"

```
type VectorSpace
type Vector
```

```
predicate In : Vector v * VectorSpace V
function addV : Vector * Vector -> Vector
```

```
notation "Vector a \in U" \sim "Vector a; In(a,U)" notation "v1 + v2" \sim "addV(v1,v2)"
```

## VectorSpace U

VectorSpace U Vector u1, u2, u3, u4, u5 ∈ U

```
VectorSpace U
Vector u1, u2, u3, u4, u5 \in U
u3 := u1 + u2
```

```
VectorSpace U

Vector u1, u2, u3, u4, u5 ∈ U

u3 := u1 + u2

u5 := u3 + u4
```

```
VectorSpace U

Vector u1, u2, u3, u4, u5 ∈ U

u3 := u1 + u2

u5 := u3 + u4
```

```
VectorSpace U

Vector u1, u2, u3, u4, u5 ∈ U

u3 := u1 + u2

u5 := u3 + u4
```

notation for AddV



## VectorSpace U

VectorSpace U Vector u1, u2, u3, u4, u5 ∈ U

```
VectorSpace U
Vector u1, u2, u3, u4, u5 \in U
u3 := u1 + u2
```

```
VectorSpace U

Vector u1, u2, u3, u4, u5 ∈ U

u3 := u1 + u2

u5 := u3 + u4
```

For every vector in a vector space,

For every vector in a vector space,

```
Vector V
with VectorSpace U
where ∨ ∈ U {
```

For every vector in a vector space,

Vector V with VectorSpace U where ∨ ∈ U {

draw it as a little arrow rooted at the origin

For every vector in a vector space,

draw it as a little arrow rooted at the origin

```
Vector V
with VectorSpace U
where v ∈ U {
   v.shape = Arrow {
      start = U.shape.center
}
```

}

For every vector in a vector space,

draw it as a little arrow rooted at the origin

place its label near the arrowhead

```
Vector V
with VectorSpace U
where v ∈ U {
    v.shape = Arrow {
        start = U.shape.center
    }
```

}

For every vector in a vector space,

draw it as a little arrow rooted at the origin

place its label near the arrowhead

```
Vector V
with VectorSpace U
where v ∈ U {
   v.shape = Arrow {
      start = U.shape.center
   }
   encourage nearHead(v.shape,
      v.text)
```

}

For every vector in a vector space,

draw it as a little arrow rooted at the origin

place its label near the arrowhead

make sure the vector's shape is in the vector space's shape

```
Vector V
with VectorSpace U
where v ∈ U {
    v.shape = Arrow {
        start = U.shape.center
    }
    encourage nearHead(v.shape, v.text)
```

For every vector in a vector space,

draw it as a little arrow rooted at the origin

place its label near the arrowhead

make sure the vector's shape is in the vector space's shape

```
Vector V
with VectorSpace U
where v \in U \{
  v.shape = Arrow {
      start = U.shape.center
  }
  encourage nearHead(v.shape,
                      v.text)
  ensure contains(U.shape,
                    v.shape)
```

For every vector that's the sum of vectors,

For every vector that's the sum of vectors,

```
Vector u
with Vector v, w; VectorSpace U
where u := v + w; u, v, w ∈ U {
```

For every vector that's the sum of vectors,

```
Vector u
with Vector v, w; VectorSpace U
where u := v + w; u, v, w ∈ U {
```

draw the end of the arrowhead as the vector sum

For every vector that's the sum of vectors,

```
Vector u
with Vector v, w; VectorSpace U
where u := v + w; u, v, w ∈ U {
```

draw the end of the arrowhead as the vector sum

For every vector that's the sum of vectors,

```
Vector u
with Vector v, w; VectorSpace U
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```

draw the end of the arrowhead as the vector sum

using the "tip-to-tail" mnemonic for the vectors being summed

For every vector that's the sum of vectors,

```
Vector u
with Vector v, w; VectorSpace U
where u := v + w; u, v, w ∈ U {
```

draw the end of the arrowhead as the vector sum

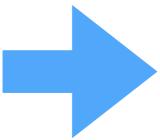
using the "tip-to-tail" mnemonic for the vectors being summed

```
u.v_shadow = Arrow {
    start = w.shape.end
    end = u.shape.end
    style = "dashed"
}

u.w_shadow = Arrow { ... }
```

Domain program

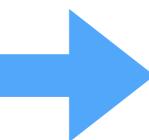
Substance program



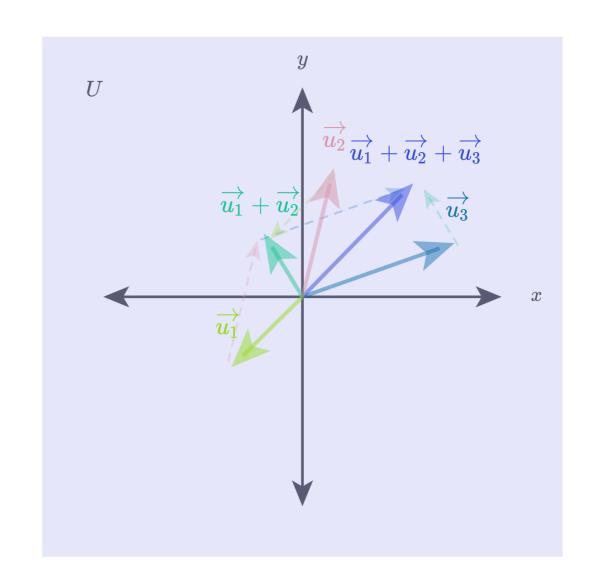
```
VectorSpace U
Vector u1, u2, u3, u4, u5 ∈ U
u3 := u1 + u2
u5 := u3 + u4
```

Domain program

Substance program

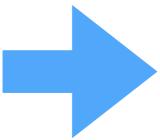


VectorSpace U
Vector u1, u2, u3, u4, u5 ∈ U
u3 := u1 + u2
u5 := u3 + u4



Domain program

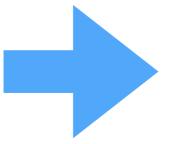
Substance program



```
VectorSpace U
Vector u1, u2, u3, u4, u5 ∈ U
u3 := u1 + u2
u5 := u3 + u4
```

Domain program

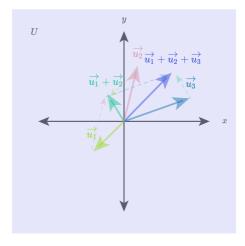
Substance program

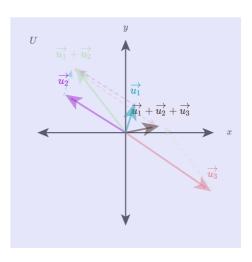


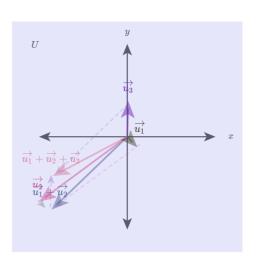
VectorSpace U Vector u1, u2, u3, u4, u5  $\in$  U

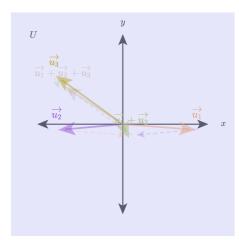
u3 := u1 + u2

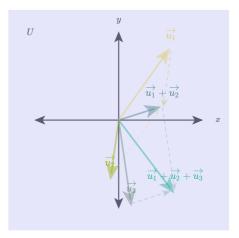
u5 := u3 + u4





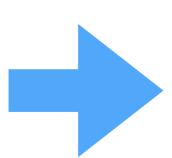


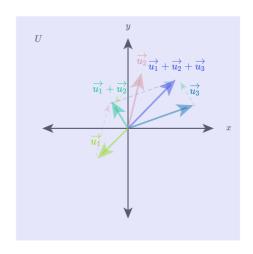


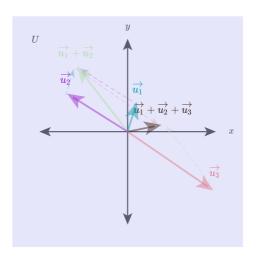


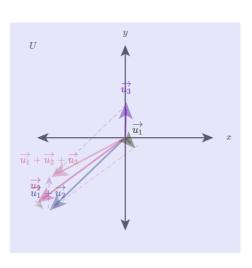
#### Key idea:

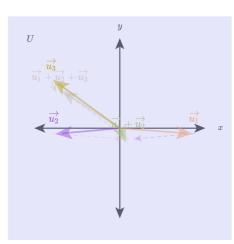
Every diagram is just one of many solutions to an underlying constrained optimization problem!

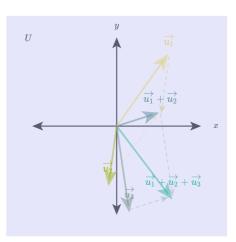












#### Example: Containment

The Style directive

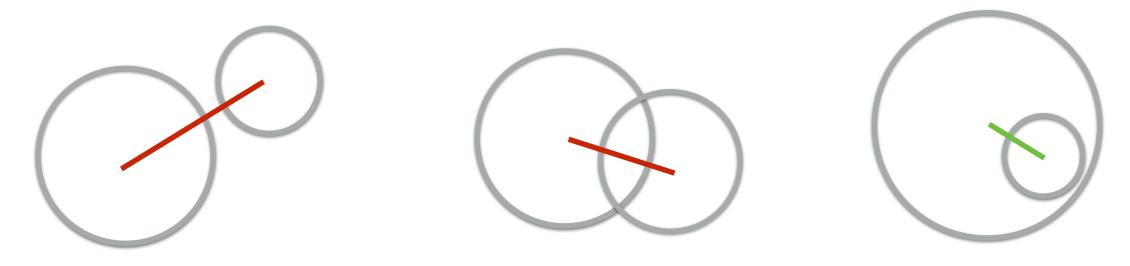
ensure Y.shape contains X.shape

#### Example: Containment

The Style directive

ensure Y.shape contains X.shape

gets automatically translated into the constraint (for circles)



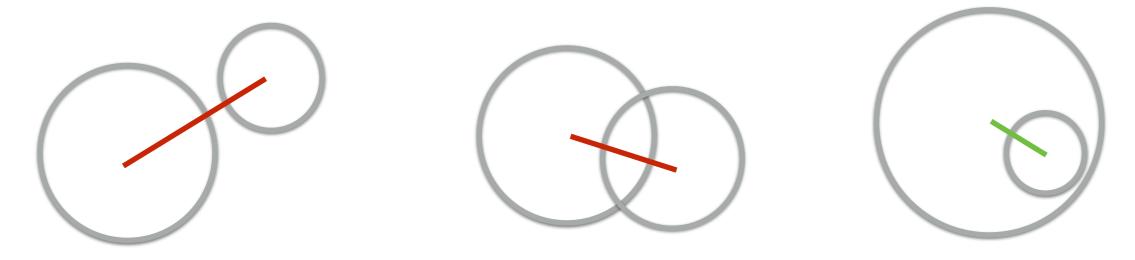
$$|c_Y - c_X| < r_Y - r_X$$

#### Example: Containment

The Style directive

ensure Y.shape contains X.shape

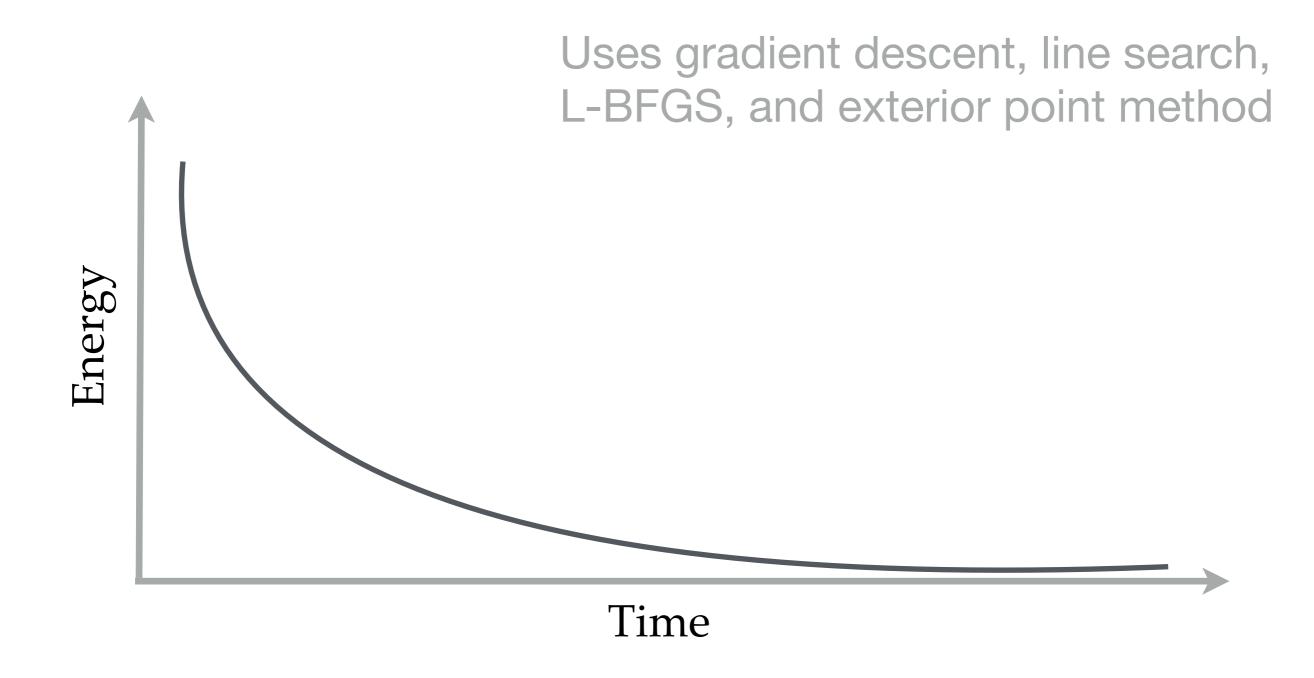
gets automatically translated into the constraint (for circles)



$$|c_Y - c_X| < r_Y - r_X$$

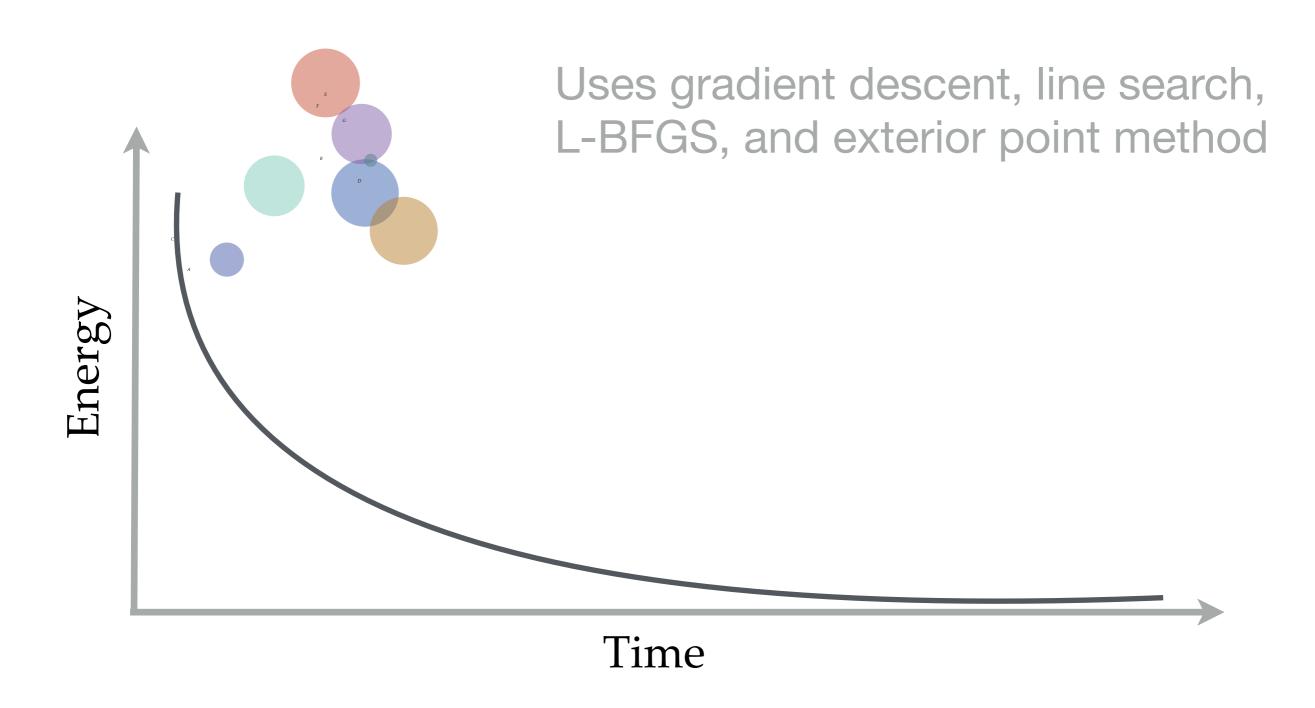
Key idea: programmer does not ever have to think this way.

#### Automatically laying out a diagram



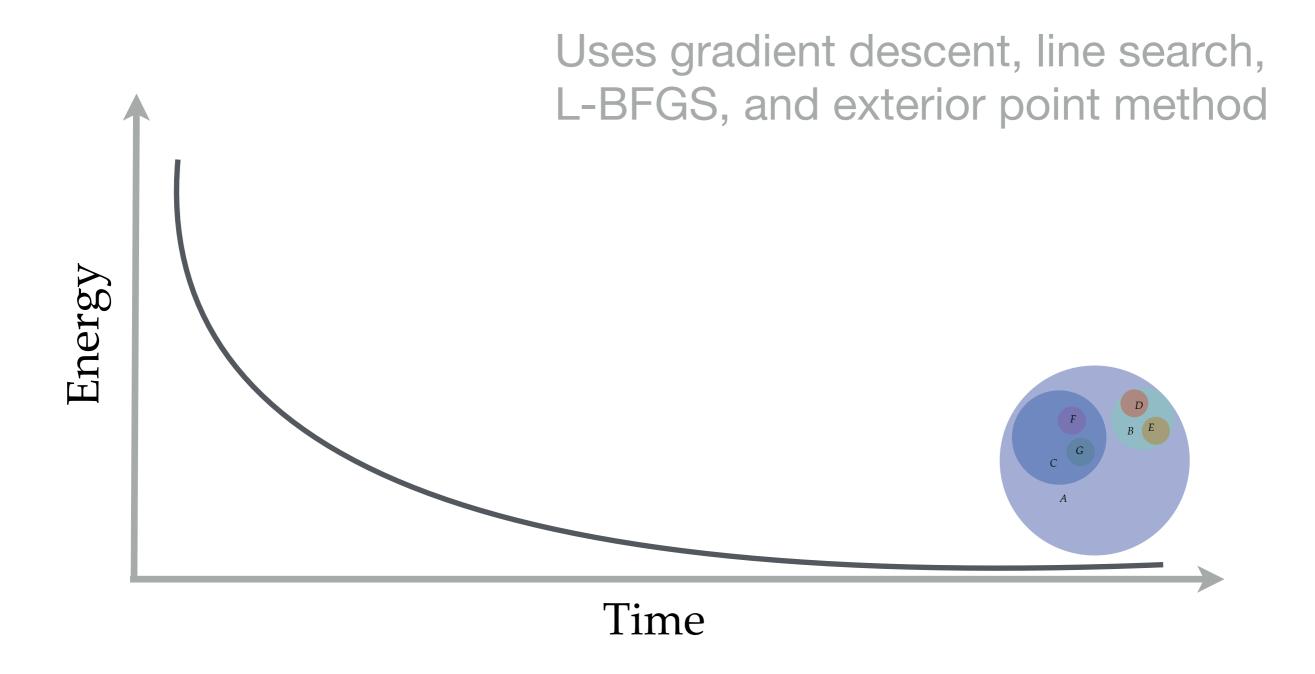
the actual energy landscape is much more complicated!

#### Automatically laying out a diagram



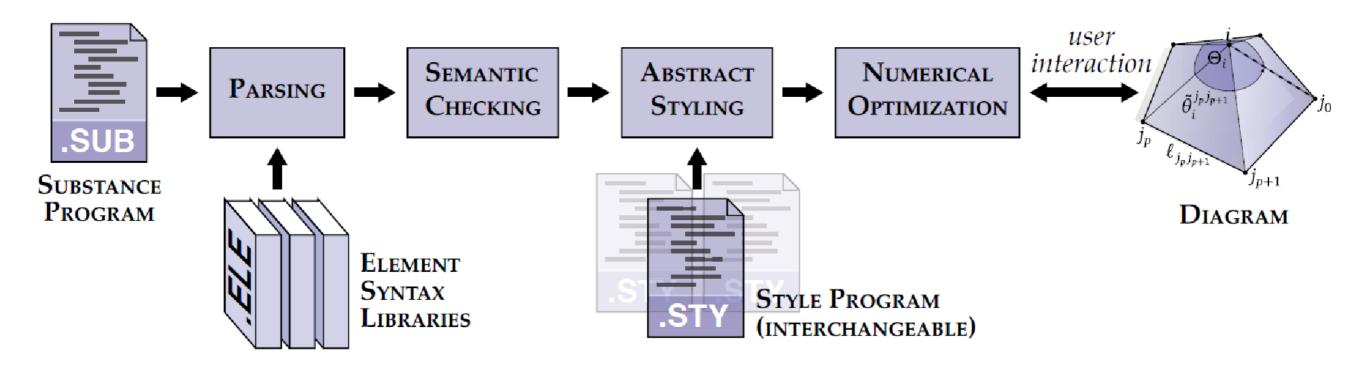
the actual energy landscape is much more complicated!

#### Automatically laying out a diagram



the actual energy landscape is much more complicated!

#### Opening up the "magical box"



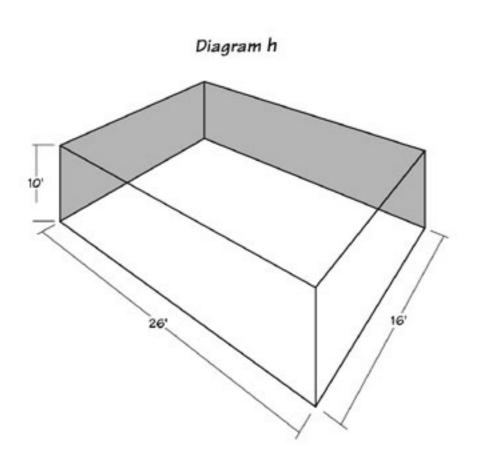
Some implementation details:

Backend written in Haskell Frontend written in Typescript + React Outputs diagrams in SVG

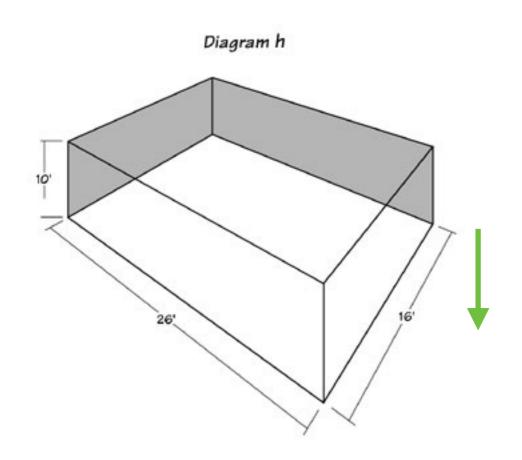
Ask me later if you're really interested!

Part IV: What does language enable?

My goal: lower the floor and raise the ceiling for making diagrams!

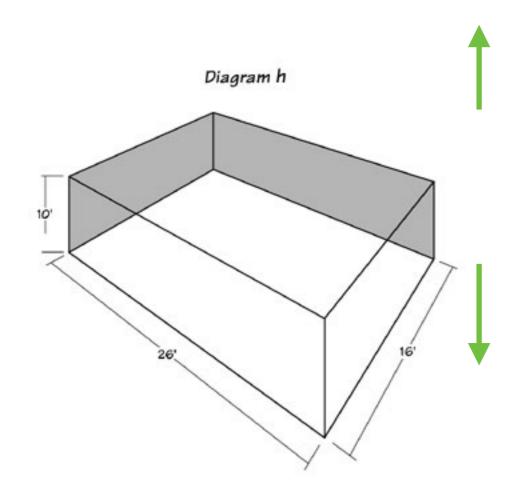


# My goal: lower the floor and raise the ceiling for making diagrams!



reduce the amount of work and expertise needed to make a diagram

# My goal: lower the floor and raise the ceiling for making diagrams!

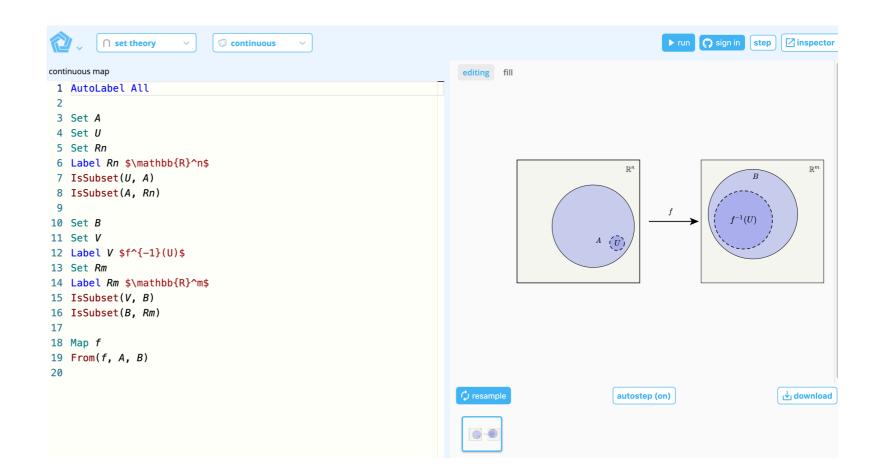


empower people to create new kinds of diagrams

reduce the amount of work and expertise needed to make a diagram

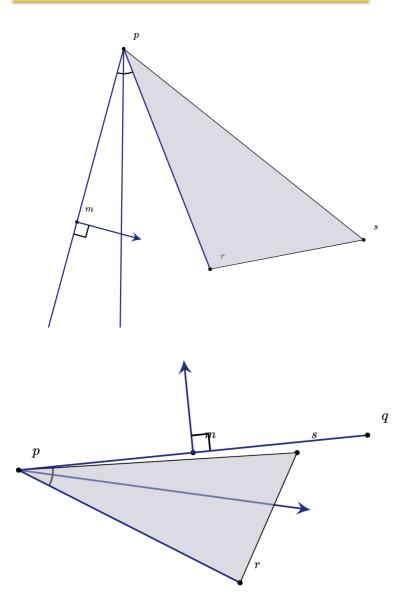
#### Some live examples

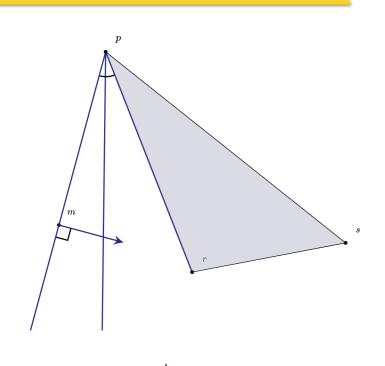
Sets
Functions
Vectors

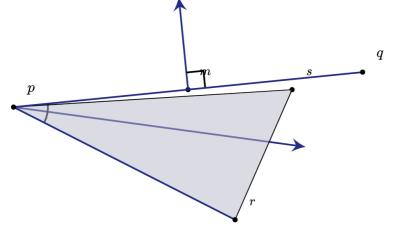


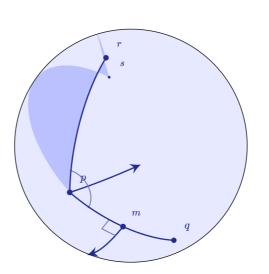
use.penrose.ink
(ALPHA)

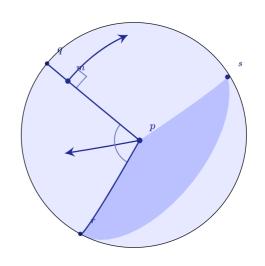


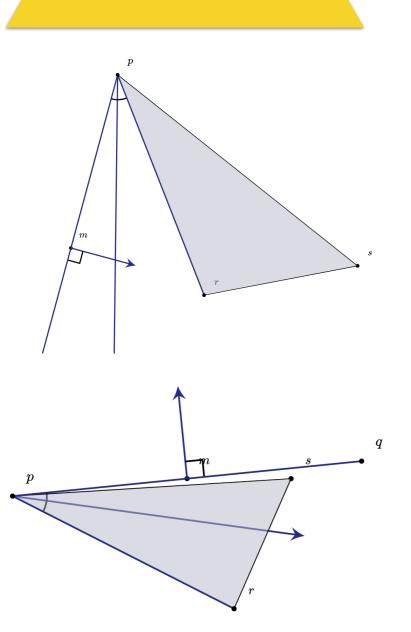


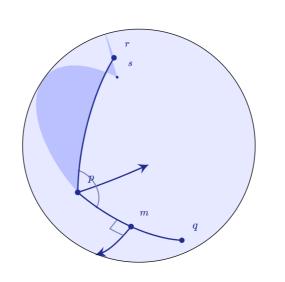


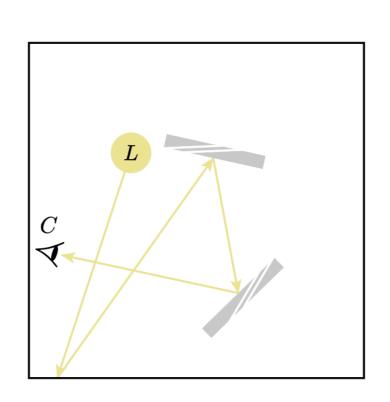


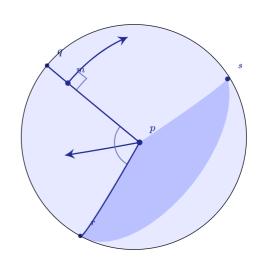


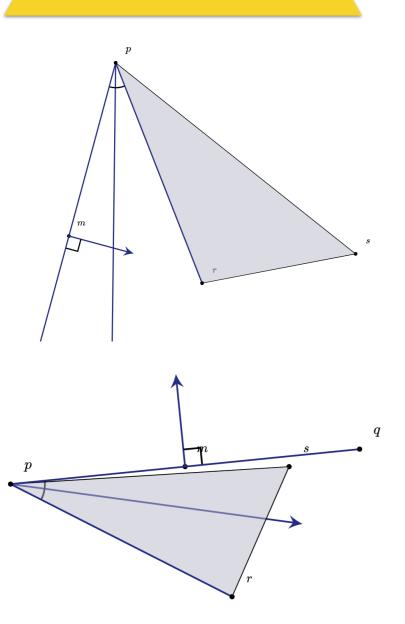


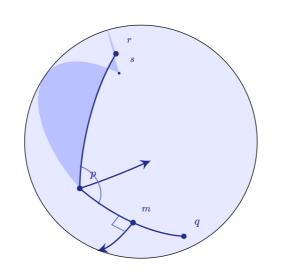


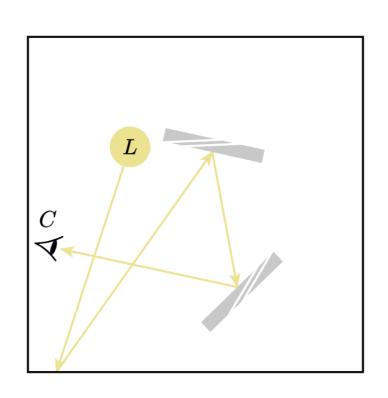


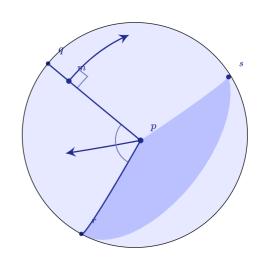


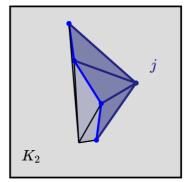


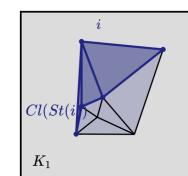


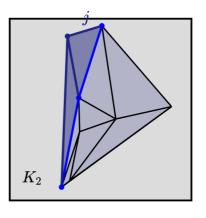


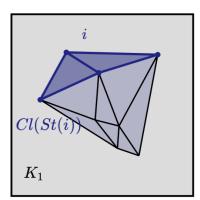










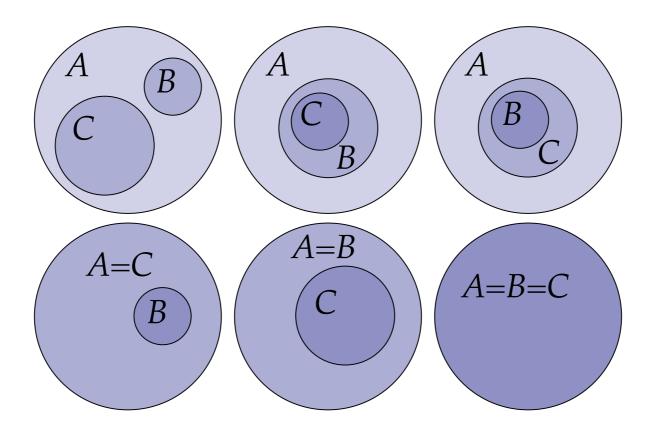


#### responsive diagrams

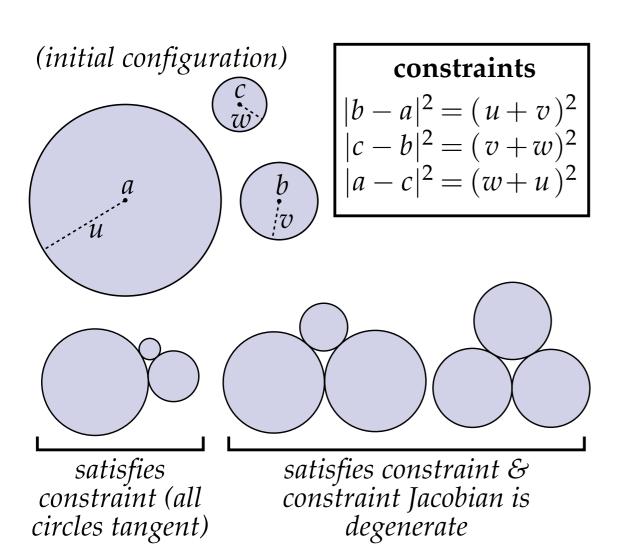


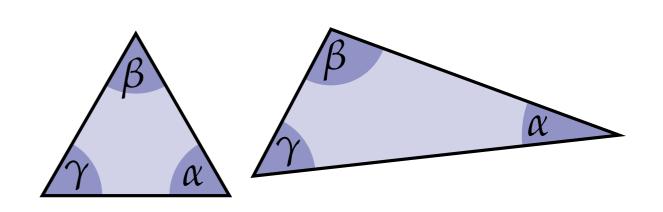
intelligently exploring the diagram space by finding different cases in the notation

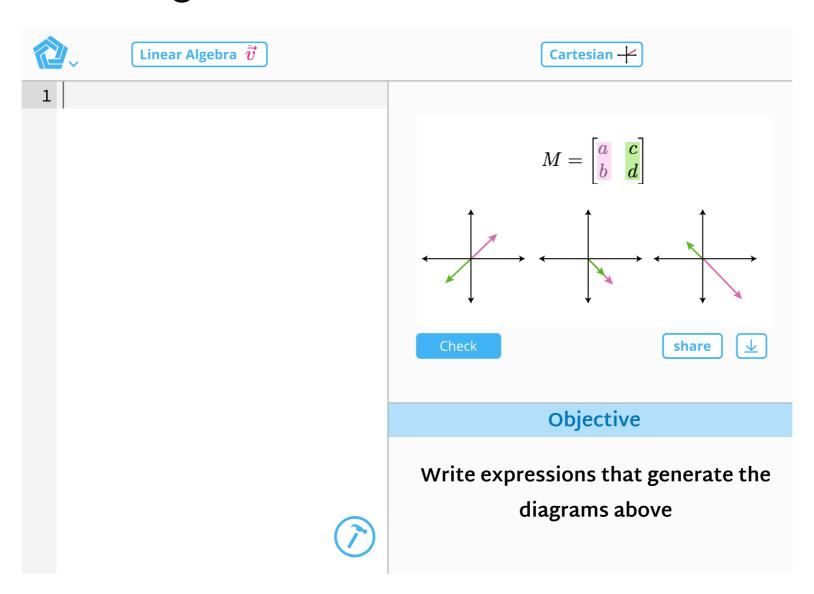
$$B, C \subset A$$

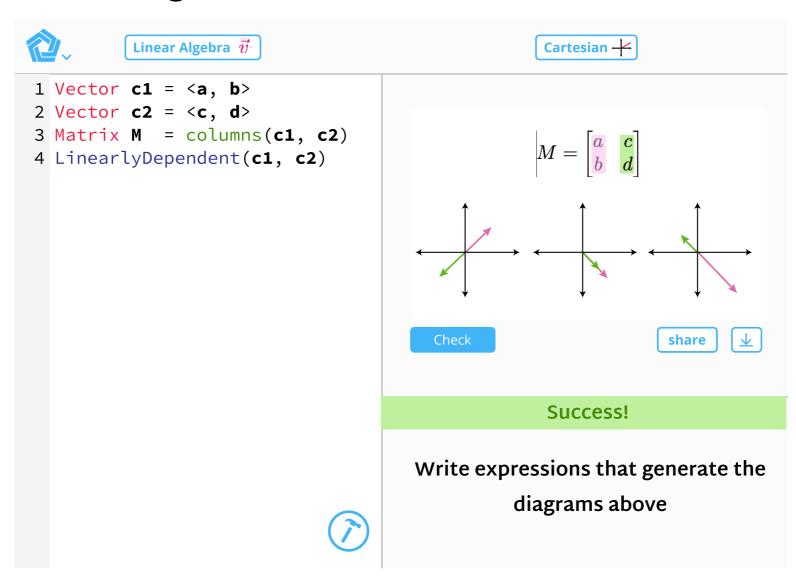


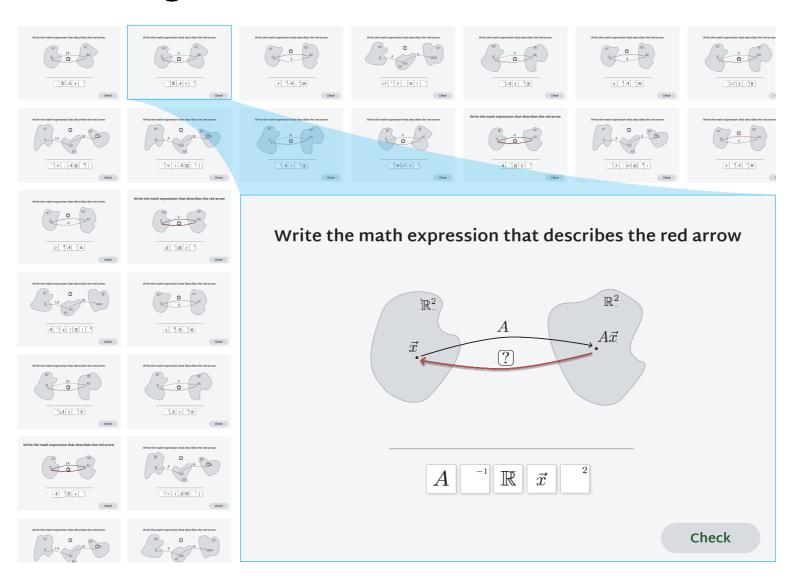
intelligently exploring the diagram space by finding different cases in the visualization

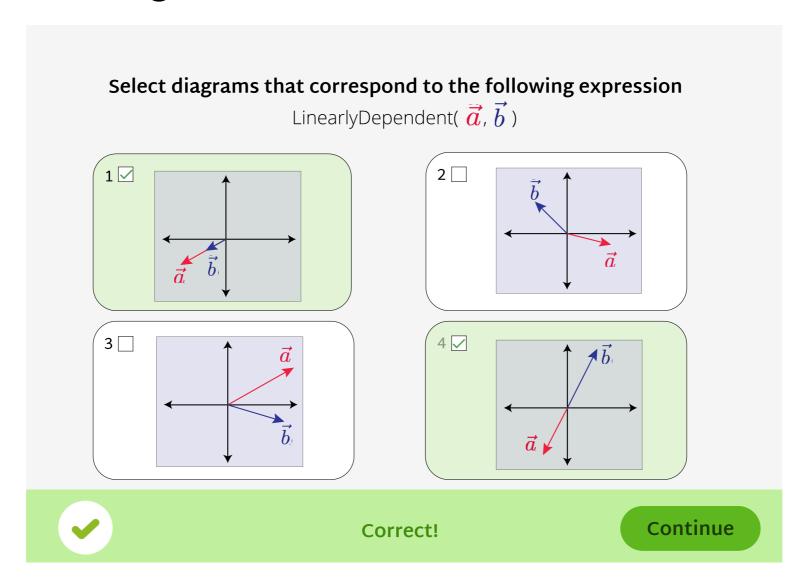






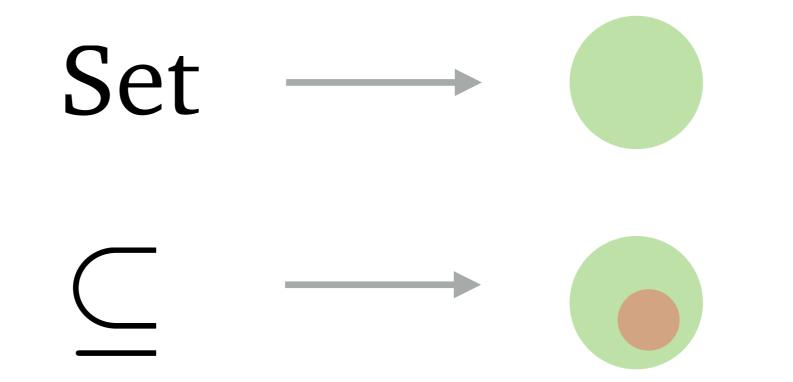






#### **Key idea**

Sets A, B, C such that  $B \subseteq A$  and  $C \subseteq A$ .



It is powerful to formally encode the **mapping** from abstract objects and relationships to their visual representations.

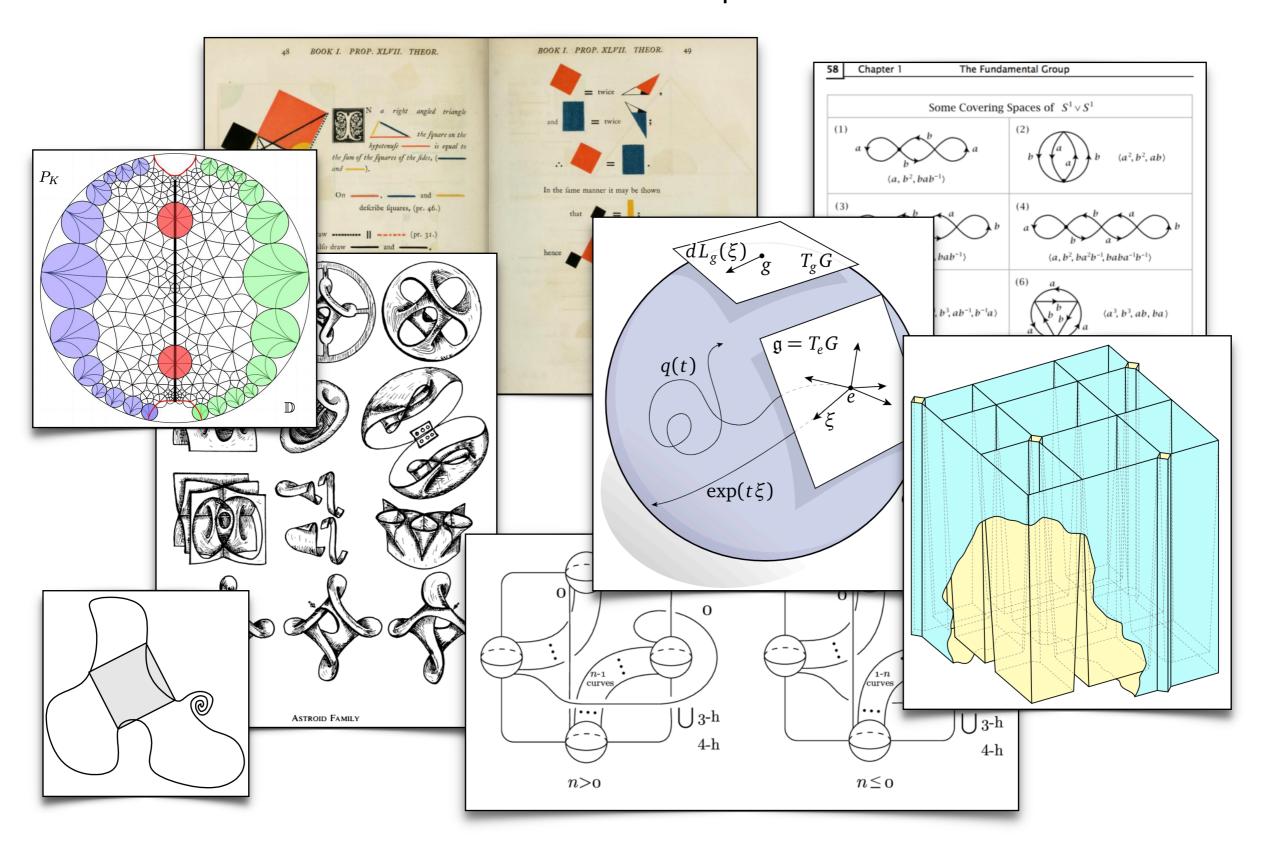
#### Thanks to my collaborators!

Wode Ni, Max Krieger, Rain Du, Dor Ma'ayan, Lily Shellhammer, Jenna Wise

advised by Keenan Crane, Jonathan Aldrich, and Joshua Sunshine



### We want to make diagrams like these the norm—not the exception!



### We want your input!

Come talk to Katherine (kqy@cs.cmu.edu)



turning mathematical notation into beautiful diagrams

http://penrose.ink
http://use.penrose.ink